# VAUTOMATIONDIRECTE 

## DL205 Installation and I/O Manual

Manual Number: D2-INST-M


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## DL205 Installation and I/O MANUAL

## VAUTOMATIONDIRECT

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| Rev. A | $04 / 01$ | added modules |
| Rev. B | $06 / 02$ | added surge suppression information and modules; updated Appendix A |
| 2nd Edition | $11 / 10$ | converted to new word processor format, added power budget, added analog wiring <br> and specs. |

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# Introduction 

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## Chapter 1: Introduction

## Introduction

## The Purpose of this Manual

Thank you for purchasing our DL205 family of products. This manual is written for the user of non-traditional CPU-slot controllers or I/O controllers who are also using AutomationDirect DL205 I/O products. This manual will show the user how to install and wire the equipment. It provides specifications for input and output modules. It also helps to understand how to interface these products to other devices in a control system.

## Where to Begin

If you already understand PLCs please read Chapter 2, "Installation, Wiring, and Specifications", and proceed on to other chapters as needed. Keep this manual handy for reference when you have questions. If you are a new DL205 customer, we suggest you read this manual completely to understand the wide variety of features in the DL205 family of products. We believe you will be pleasantly surprised with how much you can accomplish with our products.

## Supplemental Manuals

If you have purchased operator interfaces or DirectSOFT, you will need to supplement this manual with the manuals that are written for these products.

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When you see the "notepad" icon in the left-hand margin, the paragraph to its immediate right will be a special note.
The word NOTE in boldface will mark the beginning of the text.


When you see the "exclamation mark" icon in the left-hand margin, the paragraph to its immediate right will be a warning. This information could prevent injury, loss of property, or even death (in extreme cases).
The word WARNING in boldface will mark the beginning of the text.
Key Topics for Each Chapter
The beginning of each chapter will list the key topics that can be found in that chapter.


Chapter 1: Introduction

## CPU-Slot Controllers

There are currently six "base controllers" or "I/O controllers available for the DL205 hardware. Five of these are actually slave controllers and one is a stand-alone controller. These controllers allow the use of industry proven DL205 I/O for general purpose distributed applications.
The controller modules are plugged into the CPU slot of any size DL205 base. The slave controllers must be connected to a network master controller module or to a PC running PC-based control, HMI or SCADA software.
The four controllers currently available are:

- Ethernet Base Controller Module
- H2-EBC(100)(-F)
- Profibus Slave Base Controller Module
- H2-PBC
- DeviceNet ${ }^{\text {TM }}$ Slave Module
- F2-DEVNETS-1
- Smart Distributed System ${ }^{\text {TM }}$ Slave Module
- F2-SDS-1
- WinPLC
- H2-WPLCx-xx

The WinPLC uses Windows CE, a real-time operating system combined with the advantages of open standard software such as OPC, ActiveX and other Microsoft communications tools. The WinPLC only supports certain DL205 modules (consult the WinPLC User Manual).


## Chapter 1: Introduction

## DL205 System I/O Components

## Bases

Four base sizes are available: 3 slot, 4 slot, 6 slot and 9 slot. One slot is for the DL205
Controller/Slave module, the remaining slots are for I/O modules. All bases include a built-in power supply.

## I/O Configuration

The number of I/O points that can be supported is CPU-slot controller dependent.

## I/O Modules

The DL205 has some of the most powerful modules in the industry. A complete range of discrete modules which support $24 \mathrm{VDC}, 110 / 220 \mathrm{VAC}$ and up to 10A relay outputs are offered. The analog modules provide 12 and 16 bit resolution and several selections of input and output signal ranges (including bipolar).
The F2-SDS-1 and F2-DEVNETS-1 do not support specialty modules. Specialty module H2-CTRIO is supported by the other slave controllers and the H2-WPLCx-xx controller.
Installation, Wiringand Specifications
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Installing DL205 Bases ..... 2-10
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## Safety Guidelines

NOTE: Products with CE marks perform their required functions safely and adhere to relevant standards as specified by CE directives, provided they are used according to their intended purpose and that the instructions in this manual are adhered to. The protection provided by the equipment may be impaired if this equipment is used in a manner not specified in this manual. A listing of our international affiliates is available on our Web site: http://www.automationdirect.com

WARNING: Providing a safe operating environment for personnel and equipment is your responsibility and should be your primary goal during system planning and installation. Automation systems can fail and may result in situations that can cause serious injury to personnel and/or damage equipment. Do not rely on the automation system alone to provide a safe operating environment. Sufficient emergency circuits should be provided to stop either partially or totally the operation of the PLC or the controlled
 machine or process. These circuits should be routed outside the PLC in the event of controller failure, so that independent and rapid shutdown are available. Devices, such as "mushroom" switches or end of travel limit switches, should operate motor starter, solenoids, or other devices without being processed by the PLC. These emergency circuits should be designed using simple logic with a minimum number of highly reliable electromechanical components. Every automation application is different, so there may be special requirements for your particular application. Make sure all national, state, and local government requirements are followed for the proper installation and use of your equipment.

## Plan for Safety

The best way to provide a safe operating environment is to make personnel and equipment safety part of the planning process. You should examine every aspect of the system to determine which areas are critical to operator or machine safety.
If you are not familiar with PLC system installation practices, or your company does not have established installation guidelines, you should obtain additional information from the following sources.

- NEMA - The National Electrical Manufacturers Association, located in Washington, D.C., publishes many different documents that discuss standards for industrial control systems. You can order these publications directly from NEMA. Some of these include:
ICS 1, General Standards for Industrial Control and Systems
ICS 3, Industrial Systems
ICS 6, Enclosures for Industrial Control Systems
- NEC - The National Electrical Code provides regulations concerning the installation and use of various types of electrical equipment. Copies of the NEC Handbook can often be obtained from your local electrical equipment distributor or your local library.
- Local and State Agencies - many local governments and state governments have additional requirements above and beyond those described in the NEC Handbook. Check with your local Electrical Inspector or Fire Marshall office for information.


## Three Levels of Protection

The publications mentioned provide many ideas and requirements for system safety. At a minimum, you should follow these regulations. Also, you should use the following techniques, which provide three levels of system control:

- Emergency stop switch for disconnecting system power
- Mechanical disconnect for output module power
- Orderly system shutdown sequence in the PLC control program


## Emergency Stops

It is recommended that emergency stop circuits be incorporated into the system for every machine controlled by a PLC. For maximum safety in a PLC system, these circuits must not be wired into the controller, but should be hardwired external to the PLC. The emergency stop switches should be easily accessed by the operator and are generally wired into a master control relay (MCR) or a safety control relay (SCR) that will remove power from the PLC I/O system in an emergency.
MCRs and SCRs provide a convenient means for removing power from the I/O system during an emergency situation. By de-energizing an MCR (or SCR) coil, power to the input (optional) and output devices is removed. This event occurs when any emergency stop switch opens. However, the PLC continues to receive power and operate even though all its inputs and outputs are disabled.
The MCR circuit could be extended by placing a PLC fault relay (closed during normal PLC operation) in series with any other emergency stop conditions. This would cause the MCR circuit to drop the PLC I/O power in case of a PLC failure (memory error, I/O communications error, etc.).


## Chapter 2: Installation and Wiring

## Emergency Power Disconnect

A properly rated emergency power disconnect should be used to power the PLC controlled system as a means of removing the power from the entire control system. It may be necessary to install a capacitor across the disconnect to protect against a condition known as "outrush". This condition occurs when the output Triacs are turned off by powering off the disconnect, thus causing the energy stored in the inductive loads to seek the shortest distance to ground, which is often through the Triacs.
After an emergency shutdown or any other type of power interruption, there may be requirements that must be met before the PLC control program can be restarted. For example, there may be specific register values that must be established (or maintained from the state prior to the shutdown) before operations can resume. In this case, you may want to use retentive memory locations, or include constants in the control program to insure a known starting point.

## Orderly System Shutdown

Ideally, the first level of fault detection is the PLC control program, which can identify machine problems. Certain shutdown sequences should be performed. The types of problems are usually things such as jammed parts, etc. that do not pose a risk of personal injury or equipment damage.

WARNING: The control program must not be the only form of protection for any problems that may result in a risk of personal injury or equipment damage.

## Class 1, Division 2, Approval

This equipment is suitable for use in Class 1, Division 2, Zone 2, groups A, B, C and D or non-hazardous locations only.

WARNING: Explosion Hazard! Substitution of components may impair suitability for Class 1, Division 2, Zone 2.

A
WARNING: Explosion Hazard - Do not disconnect equipment unless power has been switched off or the area is known to be non-hazardous.

WARNING: All DL205 products used with connector accessories must use R/C (ECBT2) mating plugs. All mating plugs must have suitable ratings for the devices.

## Chapter 2: Installation and Wiring

## Mounting Guidelines

Before installing the PLC system you will need to know the dimensions of the components considered. The diagrams on the following pages provide the component dimensions to use in defining your enclosure specifications. Remember to leave room for potential expansion.


NOTE: If you are using other components in your system, refer to the appropriate manual to determine how those units can affect mounting dimensions.

## Base Dimensions

The following information shows the proper mounting dimensions. The height dimension is the same for all bases. The depth varies depending on your choice of I/O module. The length varies as the number of slots increase. Make sure you have followed the installation guidelines for proper spacing.

Mounting depths with:


DIN Rail slot. Use rail conforming to DIN EN 50022.

with D2-EM Expansion Unit


| Base | A <br> (Base Total Width) |  | B <br> (Mounting Hole) |  | C <br> (Component Width) |  | D <br> (Width with Exp. Unit) |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :---: |
|  | Inches | Millimeters Inches | Millimeters Inches | Millimeters | Inches | Millimeters |  |  |
|  | $6.77^{\prime \prime}$ | 172 mm | $6.41^{\prime \prime}$ | 163 mm | $5.8^{\prime \prime}$ | 148 mm | $7.24^{\prime \prime}$ |  |
| 4-slot | $7.99^{\prime \prime}$ | 203 mm | $7.63^{\prime \prime}$ | 194 mm | $7.04^{\prime \prime}$ | 179 mm | $8.46^{\prime \prime}$ |  |
| 6-slot | $10.43^{\prime \prime}$ | 265 mm | $10.07^{\prime \prime}$ | 256 mm | $9.48^{\prime \prime}$ | 241 mm | $10.90^{\prime \prime}$ |  |
| 9-slot | $14.09^{\prime \prime}$ | 358 mm | $13.74^{\prime \prime}$ | 349 mm | $13.14^{\prime \prime}$ | 334 mm | $14.56^{\prime \prime}$ |  |

## Chapter 2: Installation and Wiring

## Panel Mounting and Layout

It is important to design your panel properly to help ensure the DL205 products operate within their environmental and electrical limits. The system installation should comply with all appropriate electrical codes and standards. It is important the system also conforms to the operating standards for the application to insure proper performance. The diagrams below reference the items in the following list.


1. Mount the bases horizontally to provide proper ventilation.
2. If you place more than one base in a cabinet, there should be a minimum of 7.2 " ( 183 mm ) between bases.
3. Provide a minimum clearance of 2 " $(50 \mathrm{~mm})$ between the base and all sides of the cabinet. There should also be at least 1.2 " ( 30 mm ) of clearance between the base and any wiring ducts.
4. There must be a minimum of 2 " $(50 \mathrm{~mm})$ clearance between the panel door and the nearest DL205 component.


NOTE: The cabinet configuration below is not suitable for EU installations.
Refer to Appendix I European Union Directives.

5. The ground terminal on the DL205 base must be connected to a single point ground. Use copper stranded wire to achieve a low impedance. Copper eye lugs should be crimped and soldered to the ends of the stranded wire to ensure good surface contact. Remove anodized finishes and use copper lugs and star washers at termination points. A general rule is to achieve a 0.1 ohm of DC resistance between the DL205 base and the single point ground.
6. There must be a single point ground (i.e. copper bus bar) for all devices in the panel requiring an earth ground return. The single point of ground must be connected to the panel ground termination. The panel ground termination must be connected to earth ground. For this connection you should use \#12 AWG stranded copper wire as a minimum. Minimum wire sizes, color coding, and general safety practices should comply with appropriate electrical codes and standards for your region. A good common ground reference (Earth ground) is essential for proper operation of the DL205. There are several methods of providing an adequate common ground reference, including:
a) Installing a ground rod as close to the panel as possible.
b) Connection to incoming power system ground.
7. Properly evaluate any installations where the ambient temperature may approach the lower or upper limits of the specifications. Place a temperature probe in the panel, close the door and operate the system until the ambient temperature has stabilized. If the ambient temperature is not within the operating specification for the DL205 system, measures such as installing a cooling/heating source must be taken to get the ambient temperature within the DL205 operating specifications.
8. Device mounting bolts and ground braid termination bolts should be \#10 copper bolts or equivalent. Tapped holes instead of nut-bolt arrangements should be used whenever possible. To ensure good contact on termination areas impediments such as paint, coating or corrosion should be removed in the area of contact.
9. The DL205 system is designed to be powered by 110/220 VAC, 24 VDC , or 125 VDC normally available throughout an industrial environment. Electrical power in some areas where the PLCs are installed is not always stable and storms can cause power surges. Due to this, powerline filters are recommended for protecting the DL205 PLCs from power surges and EMI/RFI noise. The Automation Powerline Filter, for use with 120 VAC and 240 VAC, $1-5$ Amps, is an excellent choice (can be located at www.automationdirect.com), however, you can use a filter of your choice. These units install easily between the power source and the PLC.

## Enclosures

Selection of a proper enclosure is important to ensure safe and proper operation of your DL205 system. Applications of DL205 systems vary and may require additional features. The minimum considerations for enclosures include:

- Conformance to electrical standards
- Protection from the elements in an industrial environment
- Common ground reference
- Maintenance of specified ambient temperature
- Access to equipment
- Security or restricted access
- Sufficient space for proper installation and maintenance of equipment


## Chapter 2: Installation and Wiring

## Environmental Specifications

The following table lists the environmental specifications that generally apply to the DL205 system (CPU, Bases, I/O Modules). The ranges that vary for the Handheld Programmer are noted at the bottom of this chart. I/O module operation may fluctuate depending on the ambient temperature and your application. Please refer to the appropriate I/O module specifications for the temperature derating curves applying to specific modules.

| Specification | Rating |
| :--- | :--- |
| Storage temperature | $-4^{\circ} \mathrm{F}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ} \mathrm{C}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Ambient operating temperature | $32^{\circ} \mathrm{F}$ to $131^{\circ} \mathrm{F}\left(0^{\circ} \mathrm{C}\right.$ to $\left.55^{\circ} \mathrm{C}\right)$ |
| Ambient humidity** | $30 \%-95 \%$ relative humidity (non-condensing) |
| Vibration resistance | MIL STD 810 C , Method 514.2 |
| Shock resistance | MIL STD 810 C, Method 516.2 |
| Noise immunity | NEMA (ICS3-304) |
| Atmosphere | No corrosive gases |

* Operating temperature for the Handheld Programmer and the DV-1000 is $32^{\circ}$ to $122^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.50^{\circ} \mathrm{C}\right)$ Storage temperature for the Handheld Programmer and the DV-1000 is $-4^{\circ}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$.
** Equipment will operate below $\mathbf{3 0 \%}$ humidity. However, static electricity problems occur much more frequently at lower humidity levels. Make sure you take adequate precautions when you touch the equipment. Consider using ground straps, anti-static floor coverings, etc., if you use the equipment in low humidity environments.


## Power

The power source must be capable of supplying voltage and current complying with the base power supply specifications.

| Specification | AC Powered Bases | 24 VDC Powered Bases | 125 VDC Powered Bases |
| :---: | :---: | :---: | :---: |
| Part Numbers | $\begin{aligned} & \text { D2-03B-1 } \\ & \text { D204B-1 } \\ & \text { D2-06B-1 } \\ & \text { D2-09B-1 } \end{aligned}$ | $\begin{aligned} & \text { D2-03BDC1-1 } \\ & \text { D2-04DC1-1 } \\ & \text { D2-06DC1-1 } \\ & \text { 2-09BDC1- } \end{aligned}$ | $\begin{aligned} & \text { D2-06BDC2-1 } \\ & \text { D2-09BDC2-1 } \end{aligned}$ |
| Input Voltage Range | $\begin{aligned} & 100-240 \text { VAC }(+10 \% /-15 \%) \\ & 50 / 60 \mathrm{~Hz} \end{aligned}$ | $10.2-28.8 \mathrm{VDC}$ (24VDC) with less than $10 \%$ ripple | $\begin{aligned} & 104-240 \text { VDC } \\ & +10 \%-15 \% \end{aligned}$ |
| Maximum Inrush Current | 30A | 10A | 20A |
| Maximum Power | 80VA | 25W | 30W |
| Voltage Withstand (dielectric) | 1 minute @ 1500 VAC between primary, secondary, and field ground |  |  |
| Insulation Resistance | $>10 \mathrm{M} \Omega$ at 500 VDC |  |  |
| Auxiliary 24 VDC Output | $20-28 \mathrm{VDC}$, less than 1 V p-p 300mA max. | None | 20-28 VDC, less than 1V p-p 300mA max. |
| Fusing (internal to base power supply) | non-replaceable 2A @ 250V <br> slow blow fuse; external fusing recommended | non-replaceable 3.15A @ 250V slow blow fuse; external fusing recommended | non-replaceable 2A @ 250V slow blow fuse; external fusing recommended |

## Chapter 2: Installation and Wiring

## Marine Use

American Bureau of Shipping (ABS) certification requires flame-retarding insulation as per 4-8-3/5.3.6(a). ABS will accept Navy low smoke cables, cable qualified to NEC "Plenum rated" (fire resistant level 4), or other similar flammability resistant rated cables. Use cable specifications for your system that meet a recognized flame retardant standard (i.e. UL, IEEE, etc.), including evidence of cable test certification (i.e. tests certificate, UL file number, etc.).

NOTE: Wiring needs to be "low smoke" per the above paragraph. Teflon coated wire is also recommended.

## Agency Approvals

Some applications require agency approvals. Typical agency approvals which your application may require are:

- UL (Underwriters' Laboratories, Inc.)
- CSA (Canadian Standards Association)
- FM (Factory Mutual Research Corporation)
- CUL (Canadian Underwriters' Laboratories, Inc.)


## 24 VDC Power Bases

Follow these additional installation guidelines when installing D2-03BDC1-1, D2-04BDC1-1, D2-06BDC1-1 and D2-09BDC1-1 bases:

- Install these bases in compliance with the enclosure, mounting, spacing, and segregation requirements of the ultimate application.
- These bases must be used within their marked ratings.
- These bases are intended to be installed within an enclosure rated at least IP54.
- provisions should be made to prevent the rated voltage being exceeded by transient disturbances of more than $40 \%$.


## Chapter 2: Installation and Wiring

## Installing DL205 Bases

## Choosing the Base Type

The DL205 system offers four different sizes of bases and three different power supply options.
The following diagram shows an example of a 6 -slot base.


Your choice of base depends on three things:

- Number of I/O modules required
- Input power requirement (AC or DC power)
- Available power budget


## Mounting the Base

All I/O configurations of the DL205 may use any of the base configurations. The bases are secured to the equipment panel or mounting location using four M4 screws in the corner tabs of the base. The full mounting dimensions are given in the previous section on Mounting Guidelines.


?
WARNING: To minimize the risk of electrical shock, personal injury, or equipment damage, always disconnect the system power before installing or removing any system component.

## Chapter 2: Installation and Wiring

## Using Mounting Rails

The DL205 bases can also be secured to the cabinet by using mounting rails. You should use rails that conform to DIN EN standard 50022 . Refer to our catalog for a complete line of DIN rail, DINnectors and DIN rail mounted apparatus. These rails are approximately 35 mm high, with a depth of 7.5 mm . If you mount the base on a rail, you should also consider using end brackets on each end of the rail. The end brackets help keep the base from sliding horizontally along the rail. This helps minimize the possibility of accidentally pulling the wiring loose.
If you examine the bottom of the base, you'll notice small retaining clips. To secure the base to a DIN rail, place the base onto the rail and gently push up on the retaining clips. The clips lock the base onto the rail.
To remove the base, pull down on the retaining clips, lift up on the base slightly, and pull it away from the rail.

## DIN Rail Dimensions



## Chapter 2: Installation and Wiring

## Installing Components in the Base

To insert components into the base: first slide the module retaining clips to the out position and align the PC board(s) of the module with the grooves on the top and bottom of the base. Push the module straight into the base until it is firmly seated in the backplane connector. Once the module is inserted into the base, push in the retaining clips to firmly secure the module to the base.


WARNING: Minimize the risk of electrical shock, personal injury, or equipment damage. Always disconnect the system power before installing or removing any system component.

## Base Wiring Guidelines

Base Wiring

The diagrams show the terminal connections located on the power supply of the DL205 bases. The base terminals can accept up to 16 AWG. You may be able to use larger wiring depending on the type of wire used, but 16 AWG is the recommended size. Do not overtighten the connector screws; the recommended torque value is 7.81 lb -in $(0.882 \mathrm{~N} \bullet \mathrm{~m})$.


NOTE: You can connect either a 115 VAC or 220 VAC supply to the AC terminals. Special wiring or jumpers are not required as with some of the other DirectLOGIC. products.

12/24 VDC Base Terminal Strip


125 VDC Base Terminal Strip


WARNING: Once the power wiring is connected, install the plastic protective cover. When the cover is removed, there is a risk of electrical shock if you accidentally touch the wiring or wiring terminals.

## I/O Wiring and Specifications



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## Chapter 3: I/O Wiring and Specifications

## I/O Wiring Strategies

The DL205 PLC system is very flexible and will work in many different wiring configurations. By studying this section before actual installation, you can probably find the best wiring strategy for your application. This will help to lower system cost, wiring errors, and avoid safety problems.

## PLC Isolation Boundaries

PLC circuitry is divided into three main regions separated by isolation boundaries, shown in the drawing below. Electrical isolation provides safety, so that a fault in one area does not damage another. A powerline filter will provide isolation between the power source and the power supply. A transformer in the power supply provides magnetic isolation between the primary and secondary sides. Opto-couplers provide optical isolation in Input and Output circuits. This isolates logic circuitry from the field side, where factory machinery connects. Note the discrete inputs are isolated from the discrete outputs, because each is isolated from the logic side. Isolation boundaries protect the operator interface (and the operator) from power input faults or field wiring faults. When wiring a PLC, it is extremely important to avoid making external connections that connect logic side circuits to any other.


In addition to the basic circuits covered above, AC-powered and 125 VDC bases include an auxiliary +24 VDC power supply with its own isolation boundary. Since the supply output is isolated from the other three circuits, it can power input and/or output circuits!


## Powering I/O Circuits with the Auxiliary Supply

In some cases, using the built-in auxiliary +24 VDC supply can result in a cost savings for your control system. It can power combined loads up to 300 mA . Be careful not to exceed the current rating of the supply. If you are the system designer for your application, you may be able to select and design in field devices which can use the +24 VDC auxiliary supply.
All AC powered and 125 VDC DL205 bases feature the internal auxiliary supply. If input devices AND output loads need +24 VDC power, the auxiliary supply may be able to power both circuits as shown in the following diagram.

AC Power or 125VDC Bases


The 12/24VDC powered DL205 bases are designed for application environments in which low-voltage DC power is more readily available than AC. These include a wide range of battery-powered applications, such as remotely-located control, in vehicles, portable machines, etc. For this application type, all input devices and output loads typically use the same DC power source. Typical wiring for DC-powered applications is shown in the following diagram.


## Chapter 3: I/O Wiring and Specifications

## Powering I/O Circuits Using Separate Supplies

In most applications it will be necessary to power the input devices from one power source, and to power output loads from another source. Loads often require high-energy AC power, while input sensors use low-energy DC. If a machine operator is likely to come in close contact with input wiring, then safety reasons also require isolation from high-energy output circuits. It is most convenient if the loads can use the same power source as the PLC, and the input sensors can use the auxiliary supply, as shown to the left in the figure below.
If the loads cannot be powered from the PLC supply, then a separate supply must be used as shown to the right in the figure below.


Some applications will use the PLC external power source to also power the input circuit. This typically occurs on DC-powered PLCs, as shown in the drawing below to the left. The inputs share the PLC power source supply, while the outputs have their own separate supply. A worst-case scenario, from a cost and complexity viewpoint, is an application which requires separate power sources for the PLC, input devices, and output loads. The wiring diagram example below on the right shows how this can work, but the auxiliary supply output is an unused resource. You will want to avoid this situation, if possible.


## Sinking / Sourcing Concepts

Before going further in the study of wiring strategies, you must have a solid understanding of "sinking" and "sourcing" concepts. Use of these terms occurs frequently in input or output circuit discussions. It is the goal of this section to make these concepts easy to understand, further ensuring your success in installation. First the following short definitions are provided, followed by practical applications.
Sinking = provides a path to supply ground (-)

## Sourcing = provides a path to supply source (+)

First you will notice these are only associated with DC circuits and not AC, because of the reference to $(+)$ and ( - ) polarities. Therefore, sinking and sourcing terminology only applies to DC input and output circuits. Input and output points that are sinking only or sourcing only can conduct current in only one direction. This means it is possible to connect the external supply and field device to the I/O point with current trying to flow in the wrong direction, and the circuit will not operate. However, you can successfully connect the supply and field device every time by understanding "sourcing" and "sinking".
For example, the figure to the right depicts a "sinking" input. To properly connect the external supply, you will have to connect it so the input provides a path to ground (-). Start at the PLC input terminal, follow through the input sensing circuit, exit at the common terminal, and connect the supply $(-)$ to the common terminal. By adding the switch, between the supply (+) and the input, the circuit has been completed.


Current flows in the direction of the arrow when the switch is closed.
Apply the circuit principle above to the four possible combinations of input/output sinking/sourcing types as shown below. The I/O module specifications at the end of this chapter list the input or output type.


## Chapter 3: I/O Wiring and Specifications

## I/O "Common" Terminal Concepts

In order for a PLC I/O circuit to operate, current must enter at one terminal and exit at another. Therefore, at least two terminals are associated with every I/O point. In the figure to the right, the Input or Output terminal is the main path for the current. One additional terminal must provide the return path to the power supply.

If there was unlimited space and budget for I/O terminals, every I/O point could have two dedicated terminals as the figure above shows. However, providing this level of flexibility is not practical or even necessary for most applications. So, most Input or Output points on PLCs are in groups which share the return path (called commons). The figure to the right shows a group (or bank) of four input points which share a common return path. In this way, the four inputs require only five terminals instead of eight.


NOTE: In the circuit above, the current in the common path is 4 times any channel's input current when all inputs are energized. This is especially important in output circuits, where heavier gauge wire is sometimes necessary on commons.

Most DL205 input and output modules group their I/O points into banks that share a common return path. The best indication of I/O common grouping is on the wiring label, such as the one shown to the right. There are two circuit banks with eight input points in each. The common terminal for each is labeled "CA" and "CB", respectively.
In the wiring label example, the positive terminal of a DC supply connects to the common terminals. Some symbols you will see on the wiring labels, and their meanings are:
AC supply $\quad D C$ supply $\quad A C$ or $D C$ supply


Input Switch
Output Load


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## Chapter 3: I/O Wiring and Specifications

## Connecting DC I/O to "Solid State" Field Devices

In the previous section on Sourcing and Sinking concepts, the DC I/O circuits were explained to sometimes only allow current to flow one way. This is also true for many of the field devices which have solid-state (transistor) interfaces. In other words, field devices can also be sourcing or sinking. When connecting two devices in a series DC circuit, one must be wired as sourcing and the other as sinking.

## Solid State Input Sensors

Several DL205 DC input modules are flexible because they detect current flow in either direction, so they can be wired as either sourcing or sinking. In the following circuit, a field device has an open-collector NPN transistor output. It sinks current from the PLC input point, which sources current. The power supply can be the +24 auxiliary supply or another supply ( +12 VDC or +24 VDC ), as long as the input specifications are met.


In the next circuit, a field device has an open-collector PNP transistor output. It sources current to the PLC input point, which sinks the current back to ground. Since the field device is sourcing current, no additional power supply is required.


## Solid State Output Loads

Sometimes an application requires connecting a PLC output point to a solid state input on a device. This type of connection is usually made to carry a low-level control signal, not to send DC power to an actuator.
Several of the DL205 DC output modules are the sinking type. This means that each DC output provides a path to ground when it is energized. In the following circuit, the PLC output point sinks current to the output common when energized. It is connected to a sourcing input of a field device input.


## Chapter 3: I/O Wiring and Specifications

In the next example a PLC sinking DC output point is connected to the sinking input of a field device. This is a little tricky, because both the PLC output and field device input are sinking type. Since the circuit must have one sourcing and one sinking device, a sourcing capability needs to be added to the PLC output by using a pull-up resistor. In the circuit below, an $\mathrm{R}_{\text {pull-up }}$ is connected from the output to the DC output circuit power input.


NOTE 1: DO NOT attempt to drive a heavy load (>25 mA) with this pull-up method
NOTE 2: Using the pull-up resistor to implement a sourcing output has the effect of inverting the output point logic. In other words, the field device input is energized when the PLC output is OFF, from a ladder logic point of view. Your ladder program must comprehend this and generate an inverted output. Or, you may choose to cancel the effect of the inversion elsewhere, such as in the field device.

It is important to choose the correct value of $\mathrm{R}_{\text {pull-up. }}$. In order to do so, you need to know the nominal input current to the field device ( $\mathrm{I}_{\text {input }}$ ) when the input is energized. If this value is not known, it can be calculated as shown (a typical value is 15 mA ). Then use $\mathrm{I}_{\text {input }}$ and the voltage of the external supply to compute $\mathrm{R}_{\text {pull-up. }}$. Then calculate the power $\mathrm{P}_{\text {pull-up }}$ (in watts), in order to size $R_{\text {pull-up }}$ properly.

$$
\begin{aligned}
& I_{\text {input }}=\frac{V_{\text {input (turn-on) }}}{R_{\text {input }}} \\
& R_{\text {pull-up }}=\frac{V_{\text {supply }}-0.7}{I_{\text {input }}}-R_{\text {input }} \quad P_{\text {pull-up }}=\frac{V_{\text {supply }}{ }^{2}}{R_{\text {pullup }}}
\end{aligned}
$$

Of course, the easiest way to drive a sinking input field device as shown below is to use a DC sourcing output module. The Darlington NPN stage will have about 1.5 V ON-state saturation, but this is not a problem with low-current solid-state loads.

PLC DC Sourcing Output


## Relay Output Guidelines

Several output modules in the DL205 I/O family feature relay outputs: D2-04TRS, D2-08TR, D2-12TR, D2-08CDR, F2-08TR and F2-08TRS. Relays are best for the following applications:

- Loads that require higher currents than the solid-state outputs can deliver
- Cost-sensitive applications
- Some output channels need isolation from other outputs (such as when some loads require different voltages than other loads)
Some applications in which NOT to use relays:
- Loads that require currents under 10 mA
- Loads which must be switched at high speed or heavy duty cycle

Relay outputs in the DL205 output modules are available in two contact arrangements, shown to the right. The Form A type, or SPST (single pole, single throw) type is normally open and is the simplest to use. The Form C type, or SPDT (single pole, double throw) type has a center contact which moves and a stationary contact on either side. This provides a normally closed contact and a normally open contact.
Some relay output modules relays share common terminals, which connect to the wiper contact in each relay of the bank. Other relay modules have relays which are completely isolated from each other. In all cases, the module drives the relay coil when the corresponding output point is on.

## Surge Suppression For Inductive Loads

Relay with Form A contacts


Relay with Form C contacts


Inductive load devices (devices with a coil) generate transient voltages when de-energized with a relay contact. When a relay contact is closed it, "bounces", which energizes and de-energizes the coil until the "bouncing" stops. The transient voltages generated are much larger in amplitude than the supply voltage, especially with a DC supply voltage.
When switching a DC-supplied inductive load, the full supply voltage is always present when the relay contact opens (or "bounces"). When switching an AC-supplied inductive load, there are two (2) points when the voltage is zero (0) in one complete cycle of a sine wave; therefore, there are two (2) chances in $60(60 \mathrm{~Hz})$ or $50(50 \mathrm{~Hz})$ to stop the current flow at a zero crossover point. If current flow isn't stopped, the relay contact will open (or "bounce"). If the voltage is not zero when the relay contact opens, there is energy stored in the inductor that is released when the voltage to the inductor is suddenly removed. This release of energy is the cause of the transient voltages.
When inductive load devices (motors, motor starters, interposing relays, solenoids, valves, etc.) are controlled with relay contacts, it is recommended that a surge suppression device be connected directly across the coil of the field device. If the inductive device has plug-type connectors, the suppression device can be installed on the terminal block of the relay output.

## Chapter 3: I/O Wiring and Specifications

Transient Voltage Suppressors (TVS or transorb) provide the best surge and transient suppression of AC and DC powered coils, providing the fastest response with the smallest overshoot.
Metal Oxide Varistors (MOV) provide the next best surge and transient suppression of AC and DC powered coils.
For example, the waveform in the figure below shows the energy released when opening a contact switching a 24 VDC solenoid. Notice the large voltage spike.


This figure shows the same circuit with a transorb (TVS) across the coil. Notice that the voltage spike is significantly reduced.


Use the following table to help select a TVS or MOV suppressor for your application based on the inductive load voltage.

| Vendor / Catalog | Suppressor Types | Inductive Load Voltage | Part Number |
| :---: | :---: | :---: | :---: |
| AutomationDirectTransient VoltageSuppressorswww.automationdirect.com | 8-channel TVS | 24 VDC | ZL-TD8-24 |
|  | 8-channel TVS | 110 VAC | ZL-TD8-120 |
| General Instrument Transient Voltage Suppressors and LiteOn Diodes; from Digi-Key Catalog; www.digikey.com; Phone: 1-800-344-4539 | $\begin{aligned} & \text { TVS, MOV } \\ & \text { TVS, MOV } \\ & \text { TVS } \\ & \text { Diode } \end{aligned}$ | $\begin{gathered} 110 / 120 \mathrm{VAC} \\ 220 / 20 \mathrm{VAC} \\ 12 / 24 \mathrm{VDC} \text { or VAC } \\ 12 / 24 \mathrm{VDC} \text { or VAC } \end{gathered}$ | Check Digi-Key Corp. catalog or website |

## Chapter 3: I/O Wiring and Specifications

Relay contacts wear according to the amount of relay switching, amount of spark created at the time of open or closure, and presence of airborne contaminants.
However, there are some steps you can take to help prolong the life of relay contacts:

- Switch the relay on or off only when the application requires it.
- If you have the option, switch the load on or off at a time when it will draw the least current.
- Take measures to suppress inductive voltage spikes from inductive DC loads such as contactors and solenoids (circuit given below).


## PLC Relay Output

Inductive Field Device


Adding external contact protection may extend relay life beyond the number of contact cycles listed in the specification tables for relay modules. High current inductive loads such as clutches, brakes, motors, direct-acting solenoid valves, and motor starters will benefit the most from external contact protection.
The RC network must be located close to the relay module output connector. To find the values for the RC snubber network, first determine the voltage across the contacts when open, and the current through them when closed. If the load supply is AC, then convert the current and voltage values to peak values:
Now you are ready to calculate values for R and C , according to the formulas:
$\mathrm{C}(\mu \mathrm{F})=\frac{\mathrm{I}^{2}}{10} \quad \mathrm{R}(\Omega)=\frac{\mathrm{V}}{10 \mathrm{xI}^{\mathrm{x}}} \quad$, where $\mathrm{x}=1+\frac{50}{\mathrm{~V}}$
C minimum $=0.001 \mu \mathrm{~F}$, the voltage rating of C must be $\geq \mathrm{V}$, non-polarized
R minimum $=0.5 \Omega, 1 / 2 \mathrm{~W}$, tolerance is $\pm 5 \%$

## Chapter 3: I/O Wiring and Specifications

For example, suppose a relay contact drives a load at 120VAC, $1 / 2 \mathrm{~A}$. Since this example has an AC power source, first calculate the peak values:

$$
\begin{aligned}
& I_{\text {peak }}=I_{\text {rms }} \times 1.414,=0.5 \times 1.414=0.707 \text { Amperes } \\
& V_{\text {peak }}=V_{\text {rms }} \times 1.414=120 \times 1.414=169.7 \text { Volts }
\end{aligned}
$$

Now, find the values of R and C :

$$
\begin{aligned}
& C(\mu F)=\frac{I^{2}}{10}=\frac{0.707^{2}}{10}=0.05 \mu F \text {, voltage rating } \geq 170 \text { Volts } \\
& R(\Omega)=\frac{V}{10 \times I^{x}}, \text { where } x=1+\frac{50}{V} \\
& x=1+\frac{50}{169.7}=1.29 \quad R(\Omega)=\frac{169.7}{10 \times 0.707^{1.29}}=26 \Omega, 1 / 2 \mathrm{~W}, \pm 5 \%
\end{aligned}
$$

If the contact is switching a DC inductive load, add a diode across the load as near to load coil as possible. When the load is energized, the diode is reverse-biased (high impedance). When the load is turned off, energy stored in its coil is released in the form of a negativegoing voltage spike. At this moment, the diode is forward-biased (low impedance) and shunts the energy to ground. This protects the relay contacts from the high voltage arc that would occur as the contacts are opening.
For best results, follow these guidelines in using a noise suppression diode:

- DO NOT use this circuit with an AC power supply.
- Place the diode as close to the inductive field device as possible.
- Use a diode with a peak inverse voltage rating (PIV) at least 100 PIV, 3A forward current or larger. Use a fast-recovery type (such as Schottky type). DO NOT use a small-signal diode such as $1 \mathrm{~N} 914,1 \mathrm{~N} 941$, etc.
- Be sure the diode is in the circuit correctly before operation. If installed backwards, it shortcircuits the supply when the relay energizes.


## I/O Modules Position, Wiring, and Specification

## Slot Numbering

The DL205 bases each provide different numbers of slots for use with the I/O modules. You may notice the bases refer to 3 -slot, 4 -slot, etc. One of the slots is dedicated to the CPU-slot controller, so you always have one less I/O slot. For example, there are five I/O slots with a 6slot base. The I/O slots are numbered $0-4$. The CPU slot always contains a PLC CPU or a

## Module Placement Restrictions

The following table lists the valid locations for all types of modules in a DL205 system.

| Module/Unit | Local CPU Base | Local Expansion Base | Remote I/O Base |
| :---: | :---: | :---: | :---: |
| CPUs | CPU Slot Only |  |  |
| DC Input Modules | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| AC Input Modules | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| DC Output Modules | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| AC Output Modules | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Relay Output Modules | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Analog Input and Output Modules | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Local Expansion |  |  |  |
| Base Expansion Module | $\checkmark$ | $\checkmark$ |  |
| Base Controller Module |  | CPU Slot Only |  |
| Serial Remote I/O |  |  |  |
| Remote Master | $\checkmark$ |  |  |
| Remote Slave Unit |  |  | CPU Slot Only |
| Ethernet Remote Master | $\checkmark$ |  |  |
| CPU Interface |  |  |  |
| Ethernet Base Controller | Slot 0 Only |  | Slot 0 Only* |
| WinPLC | Slot 0 Only |  |  |
| DeviceNet | Slot 0 Only |  |  |
| Profibus | Slot 0 Only |  |  |
| SDS | Slot 0 Only |  |  |
| Specialty Modules |  |  |  |
| Counter Interface | Slot 0 Only |  |  |
| Counter I/O | $\checkmark$ |  | $\downarrow^{*}$ |
| Data Communications | $\checkmark$ |  |  |
| Ethernet Communications | $\checkmark$ |  |  |
| BASIC CoProcessor | $\checkmark$ |  |  |
| Simulator | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Filler | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| * When used with H2-ERM Ethernet Remote I/O system |  |  |  |

## Chapter 3: I/O Wiring and Specifications

## Special Placement Considerations for Analog Modules

In most cases, the analog modules can be placed in any slot. However, the placement can also depend on the type of CPU you are using and the other types of modules installed to the left of the analog modules. If you're using a DL230 CPU (or a DL240 CPU with firmware earlier than V1.4), you should check the DL205 Analog I/O Manual for any possible placement restrictions related to your particular module. You can order the DL205 Analog I/O Manual by ordering part number D2-ANLG-M.

## Discrete Input Module Status Indicators

The discrete modules provide LED status indicators to show the status of the input points.


## Color Coding of I/O Modules

The DL205 family of I/O modules have a color coding scheme to help you quickly identify if a module is either an input module, output module, or a specialty module. This is done through a color bar indicator located on the front of each module. The color scheme is listed below:


Color Code

| Module Type | Color Code |
| :--- | :--- |
| Discrete/Analog Output | Red |
| Discrete/Analog Input | Blue |
| Other | White |

## Wiring the Different Module Connectors

There are two types of module connectors for the DL205 I/O. Some modules have normal screw terminal connectors. Other modules have connectors with recessed screws. The recessed screws help minimize the risk of someone accidentally touching active wiring.
Both types of connectors can be easily removed. If you examine the connectors closely, you'll notice there are squeeze tabs on the top and bottom. To remove the terminal block, press the squeeze tabs and pull the terminal block away from the module.
We also have DIN rail mounted terminal blocks, DINnectors (refer to our catalog for a complete listing of all available products). ZIPLinks come with special pre-assembled cables with the I/O connectors installed and wired.
WARNING: For some modules, field device power may still be present on the terminal block even though the PLC system is turned off. To minimize the risk of electrical shock, check all field device power before you remove the connector.


## Chapter 3: I/O Wiring and Specifications

## I/O Wiring Checklist

Use the following guidelines when wiring the I/O modules in your system.

1. There is a limit to the size of wire the modules can accept. The table below lists the suggested AWG for each module type. When making terminal connections, follow the suggested torque values.

| Module type | Suggested AWG Range | Suggested Torque |
| :--- | :--- | :--- |
| 4 point | $16^{*}-24 \mathrm{AWG}$ | $7.81 \mathrm{lb}-\mathrm{inch}(0.882 \mathrm{~N} \bullet m)$ |
| 8 point | $16^{*}-24 \mathrm{AWG}$ | $7.81 \mathrm{lb}-\mathrm{inch}(0.882 \mathrm{~N} \bullet \mathrm{~m})$ |
| 12 point | $16^{*}-24 \mathrm{AWG}$ | $2.65 \mathrm{lb}-\mathrm{in}(0.3 \mathrm{~N} \cdot \mathrm{~m})$ |
| 16 point | $16^{*}-24 \mathrm{AWG}$ | $2.65 \mathrm{lb}-\mathrm{in}(0.3 \mathrm{~N} \cdot \mathrm{~m})$ |

*NOTE: 16 AWG Type TFFN or Type MTW is recommended. Other types of 16 AWG may be acceptable, but it really depends on the thickness and stiffness of the wire insulation. If the insulation is too thick or stiff and a majority of the module's I/O points are used, then the plastic terminal cover may not close properly or the connector may pull away from the module. This applies especially for high temperature thermoplastics such as THHN.
2. Always use a continuous length of wire; do not combine wires to attain a needed length.
3. Use the shortest possible wire length.
4. Use wire trays for routing where possible.
5. Avoid running wires near high energy wiring. Also, avoid running input wiring close to output wiring where possible.
6. To minimize voltage drops when wires must run a long distance, consider using multiple wires for the return line.
7. Avoid running DC wiring in close proximity to AC wiring where possible.
8. Avoid creating sharp bends in the wires.
9. To reduce the risk of having a module with a blown fuse, we suggest you add external fuses to your I/O wiring. A fast blow fuse, with a lower current rating than the I/O module fuse, can be added to each common or, a fuse with a rating of slightly less than the maximum current per output point can be added to each output. Refer to our catalog for a complete line of DINnectors, DIN rail mounted fuse blocks.


NOTE: For modules which have soldered or non-replaceable fuses, we recommend you return your module to us and let us replace your blown fuse(s) since disassembling the module will void your warranty.

## I/O Points Required for Each Module

Each type of module requires a certain number of I/O points. This is also true for some specialty modules, such as analog, counter interface, etc..

| DC Input Modules | Number of /O Pls. Required | Specialty Modules, etc. | Number of //O Pls. Required |
| :---: | :---: | :---: | :---: |
| D2-08ND3 | 8 Input | H2-ECOM(-F) | None |
| D2-16ND3-2 | 16 Input | D2-DCM | None |
| D2-32ND3(-2) | 32 Input | H2-ERM(-F) | None |
| AC Input Modules |  | H2-EBC(-F) | None |
| D2-08NA-1 | 8 Input | D2-RMSM | None |
| D2-08NA-2 | 8 Input | D2-RSSS | None |
| D2-16NA | 16 Input | F2-CP128 | None |
| DC Output Modules |  | H2-CTRIO | None |
| D2-04TD1 | 8 Output (Only the first four points are used) | D2-CTRINT | 8 Input 8 Output |
| D2-08TD1 | 8 Output | F2-DEVNETS-1 | None |
| D2-16TD1-2 (2-2) | 16 Output | H2-PBC | None |
| D2-16TD1(2)P | 16 Output | F2-SDS-1 | None |
| D2-32TD1(-2) | 32 Output | D2-08SIM | 8 Input |
| AC Output Modules |  | D2-EM | None |
| D2-08TA | 8 Output | D2-CM | None |
| F2-08TA | 8 Output | H2-ECOM(100) | None |
| D2-12TA | 16 Output (See note 1) |  |  |
| Relay Output Modules |  |  |  |
| D2-04TRS | 8 Output (Only the first four points are used) |  |  |
| D2-08TR | 8 Output |  |  |
| F2-08TRS | 8 Output |  |  |
| F2-08TR | 8 Output |  |  |
| D2-12TR | 16 Output (See note 1) |  |  |
| Combination Modules |  |  |  |
| D2-08CDR | 8 In, 8 Out (Only the first four points are used for each type) |  |  |
| Analog Modules |  |  |  |
| F2-04AD-1 \& 1L | 16 Input |  |  |
| F2-04AD-2 \& 2L | 16 Input |  |  |
| F2-08AD-1 | 16 Input |  |  |
| F2-02DA-1 \& 1L | 16 Output |  |  |
| F2-02DA-2 \& 2L | 16 Output |  |  |
| F2-08DA-1 | 16 Output |  |  |
| F2-08DA-2 | 16 Output |  |  |
| F2-02DAS-1 | 32 Output |  |  |
| F2-02DAS-2 | 32 Output |  |  |
| F2-4AD2DA | 16 Input \& 16 Output |  |  |
| F2-8AD4DA-1 | 32 Input \& 32 Output |  |  |
| F2-8AD4DA-2 | 32 Input \& 32 Output |  |  |
| F2-04RTD | 32 Input |  |  |
| F2-04THM | 32 Input |  |  |

NOTE 1: -12pt. modules consume 16 points. The first 6 points are assigned, two are skipped, and then the next 6 points are assigned. For example, a D2-12TA installed in slot 0 would use Y0-Y5, and Y-10-Y15. Y6-Y7 and Y16-Y17 would be unused.

## Chapter 3: I/O Wiring and Specifications

## Calculating the Power Budget

## Managing your Power Resource

When you determine the types and quantity of I/O modules you will be using in the DL205 system it is important to remember there is a limited amount of power available from the power supply. We have provided a chart to help you easily see the amount of power available with each base. The following chart will help you calculate the amount of power you need with your I/O selections. At the end of this section you will also find an example of power budgeting and a worksheet for your own calculations.
If the I/O you choose exceeds the maximum power available from the power supply, you may need to use local expansion bases or remote I/O bases.
WARNING: It is extremely important to calculate the power budget. If you exceed the power budget, the system may operate in an unpredictable manner which may result in a risk of personal injury or equipment damage.

| Bases | 5V Current Supplied | Auxiliary 24VDC Current Supplied |
| :--- | :--- | :--- |
| D2-03B-1 | 2600 mA | 300 mA |
| D2-04B-1 | 2600 mA | 300 mA |
| D2-06B-1 | 2600 mA | 300 mA |
| D2-09B-1 | 2600 mA | 300 mA |
| D2-03BDC1-1 | 2600 mA | None |
| D2-04BDC1-1 | 2600 mA | None |
| D2-06BDC1-1 | 2600 mA | None |
| D2-09BDC1-1 | 2600 mA | None |
| D2-06BDC2-1 | 2600 mA | 300 mA |
| D2-09BDC2-1 | 2600 mA | 300 mA |

## CPU Power Specifications

The following chart shows the amount of current available for the two voltages supplied from the DL205 base. Use these currents when calculating the power budget for your system. The Auxiliary 24 V Power Source mentioned in the table is a connection at the base terminal strip allowing you to connect to devices or DL205 modules that require 24 VDC .

## Module Power Requirements

Use the power requirements shown on the next page to calculate the power budget for your system. If an External 24 VDC power supply is required, the external 24 VDC from the base power supply may be used as long as the power budget is not exceeded.

Chapter 3: I/O Wiring and Specifications

| Power Consumed |  |  | Power Consumed |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Device | 5 V (mA) | $\begin{gathered} \text { 24V Auxilliary } \\ (\mathrm{mA}) \end{gathered}$ | Device | 5 V (mA) | $\begin{aligned} & \text { 24V Auxilliary } \\ & (\mathrm{mA}) \end{aligned}$ |
| CPUs |  |  | Combination Modules |  |  |
| D2-230 | 120 | 0 | D2-08CDR | 200 | 0 |
| D2-240 | 120 | 0 | Specialty Modules |  |  |
| D2-250-1 | 330 | 0 | H2-PBC | 530 | 0 |
| D2-260 | 330 | 0 | H2-ECOM | 450 | 0 |
| DC Input Modules |  |  | H2-ECOM100 | 300 | 0 |
| D2-08ND3 | 50 | 0 | H2-ECOM-F | 640 | 0 |
| D2-16ND3-2 | 100 | 0 | H2-ERM | 320 | 0 |
| D2-32ND3(-2) | 25 | 0 | H2-ERM-F | 450 | 0 |
| AC Input Modules |  |  | H2-EBC | 320 | 0 |
| D2-08NA-1 | 50 | 0 | H2-EBC-F | 450 | 0 |
| D2-08NA-2 | 100 | 0 | H2-CTRIO | 400 | 0 |
| D2-16NA | 100 | 0 | D2-DCM | 300 | 0 |
| DC Output Modules |  |  | D2-RMSM | 200 | 0 |
| D2-04TD1 | 60 | 20 | D2-RSSS | 150 | 0 |
| D2-08TD1(-2) | 100 | 0 | D2-CTRINT | 50* | 0 |
| D2-16TD1-2 | 200 | 80 | D2-08SIM | 50 | 0 |
| D2-16TD2-2 | 200 | 0 | D2-CM | 100 | 0 |
| D2-32TD1(-2) | 350 | 0 | D2-EM | 130 | 0 |
| AC Output Modules |  |  | F2-CP128 | 235 | 0 |
| D2-08TA | 250 | 0 | F2-DEVNETS-1 | 160 | 0 |
| F2-08TA | 250 | 0 | F2-SDS-1 | 160 | 0 |
| D2-12TA | 350 | 0 |  |  |  |
| Relay Output Modules |  |  |  |  |  |
| D2-04TRS | 250 | 0 |  |  |  |
| D2-08TR | 250 | 0 |  |  |  |
| F2-08TRS | 670 | 0 |  |  |  |
| F2-08TR | 670 | 0 |  |  |  |
| D2-12TR | 450 | 0 |  |  |  |
| Analog Modules |  |  |  |  |  |
| F2-04AD-1 | 50 | 80 | F2-02DAS-1 | 100 | 50mA per channel |
| F2-04AD-1L | 100 | 5mA @ 10-30V | F2-02DAS-2 | 100 | 60mA per channel |
| F2-04AD-2 | 110 | 5 mA @ 10-30V | F2-4AD2DA | 90 | $80 \mathrm{~mA}^{* *}$ |
| F2-04AD-2L | 60 | 90mA@12V** | F2-8AD4DA-1 | 35 | 100 |
| F2-08AD-1 | 100 | 5mA@ 10-30V | F2-8AD4DA-2 | 35 | 80 |
| F2-08AD-2 | 100 | 5mA @ 10-30V | F2-04RTD | 90 | 0 |
| F2-02DA-1 | 40 | 60** | F2-04THM | 110 | 60 |
| F2-02DA-1L | 40 | 70mA @ 12V** |  |  |  |
| F2-02DA-2 | 40 | 60 |  |  |  |
| F2-02DA-2L | 40 | 70mA @ 12V** |  |  |  |
| F2-08DA-1 | 30 | $50 \mathrm{mA**}$ |  |  |  |
| F2-08DA-2 | 60 | 140 |  |  |  |
| *requires external 5VDC for outputs <br> **add an additional 20 mA per loop |  |  |  |  |  |

## Chapter 3: I/O Wiring and Specifications

## Power Budget Calculation Example

The following example shows how to calculate the power budget for the DL205 system.


1. Use the power budget table to fill in the power requirements for all the system components. First, enter the amount of power supplied by the base. Next, list the requirements for the CPU, any I/O modules, and any other devices, such as the Handheld Programmer, C-more HMI or the DV-1000 operator interface. Remember, even though the Handheld or the DV-1000 are not installed in the base, they still obtain their power from the system. Also, make sure you obtain any external power requirements, such as the 24 VDC power required by the analog modules.
2. Add the current columns starting with CPU slot and put the total in the row labeled "Total power required"
3. Subtract the row labeled "Total power required" from the row labeled "Available Base Power". Place the difference in the row labeled "Remaining Power Available".
4. If "Total Power Required" is greater than the power available from the base, the power budget will be exceeded. It will be unsafe to use this configuration and you will need to restructure your I/O configuration.
WARNING: It is extremely important to calculate the power budget. If you exceed the power budget, the system may operate in an unpredictable manner which may result in a risk of personal injury or equipment damage.

## Power Budget Calculation Worksheet

This blank chart is provided for you to copy and use in your power budget calculations.

| Base \# <br> 0 | Module Type | 5 VDC (mA) | Auxiliary <br> Power Source <br> 24 VDC Output (mA) |
| :--- | :---: | :--- | :--- |
| Available Base Power |  |  |  |
| CPU Slot |  |  |  |
| Slot 0 |  |  |  |
| Slot 1 |  |  |  |
| Slot 2 |  |  |  |
| Slot 3 |  |  |  |
| Slot 4 |  |  |  |
| Slot 5 |  |  |  |
| Slot 6 |  |  |  |
| Slot 7 |  |  |  |
| Other |  |  |  |
| Total Power Required |  |  |  |

1. Use the power budget table to fill in the power requirements for all the system components. This includes the CPU, any I/O modules, and any other devices, such as the Handheld Programmer, C-more HMI or the DV-1000 operator interface. Also, make sure you obtain any external power requirements, such as the 24 VDC power required by the analog modules.
2. Add the current columns starting with CPU slot and put the total in the row labeled "Total power required".
3. Subtract the row labeled "Total power required" from the row labeled "Available Base Power". Place the difference in the row labeled "Remaining Power Available".
4. If "Total Power Required" is greater than the power available from the base, the power budget will be exceeded. It will be unsafe to use this configuration and you will need to restructure your I/O configuration.


WARNING: It is extremely important to calculate the power budget. If you exceed the power budget, the system may operate in an unpredictable manner which may result in a risk of personal injury or equipment damage.

## DL205 Digital Input Modules

D2-08ND3, DC Input

| Inputs per Module | 8 (sink/source) |
| :--- | :--- |
| Commons per Module | 1 (2 I/0 terminal points) |
| Input Voltage Range | $10.2-26.4 \mathrm{VDC}$ |
| Peak Voltage | 26.4 VDC |
| ON Voltage Level | 9.5 VDC minimum |
| OFF Voltage Level | 3.5 VDC maximum |
| AC Frequency | $\mathrm{N} / \mathrm{A}$ |
| Input Impedance | $2.7 \mathrm{k} \mathrm{\Omega}$ |
| Input Current | 4.0 mA @ 12 VDC |
| Minimum ON Current | 3.5 mA @ 24 VDC |
| Maximum OFF Current | 1.5 mA |
| Base Power Required 5VDC | 50 mA |
| OFF to ON Response | 1 to 8 ms |
| ON to OFF Response | 1 to 8 ms |
| Terminal Type (included) | Removable, D2-8IOCON |
| Status Indicator | Logic side |
| Weight | 2.3 oz. (65 g) |



D2-16ND3-2, DC Input

| Inputs per Module | 16 (sink/source) |
| :--- | :--- |
| Commons per Module | 2 isolated (8 I/0 terminal <br> points/com) |
| Input Voltage Range | $20-28 \mathrm{VDC}$ |
| Peak Voltage | $30 \mathrm{VDC}(10 \mathrm{~mA})$ |
| ON Voltage Level | 19 VDC minimum |
| OFF Voltage Level | 7 VDC maximum |
| AC Frequency | $\mathrm{N} / \mathrm{A}$ |
| Input Impedance | $3.9 \mathrm{k} \mathrm{\Omega}$ |
| Input Current | 6 mA @ 24 VDC |
| Minimum ON Current | 3.5 mA |
| Maximum OFF Current | 1.5 mA |
| Base Power Required 5VDC | 100 mA |
| OFF to ON Response | 3 to 9 ms |
| ON to OFF Response | 3 to 9 ms |
| Terminal Type (included) | Removable, D2-16IOCON |
| Status Indicator | Logic side |
| Weight | 2.3 oz. (65 g) |



Chapter 3: I/O Wiring and Specifications

## D2-32ND3, DC Input

| Inputs per Module | 32 (sink/source) |
| :--- | :--- |
| Commons per Module | 4 isolated (8 //O terminal points / com) |
| Input Voltage Range | $20-28 \mathrm{VDC}$ |
| Peak Voltage | 30 VDC |
| ON Voltage Level | 19 VDC minimum |
| OFF Voltage Level | 7 VDC maximum |
| AC Frequency | $\mathrm{N} / \mathrm{A}$ |
| Input Impedance | $4.8 \mathrm{k} \mathrm{\Omega}$ |
| Input Current | 8.0 mA @ 24 VDC |
| Minimum ON Current | 3.5 mA |
| Maximum OFF Current | 1.5 mA |
| Base Power Required 5VDC | 25 mA |
| OFF to ON Response | 3 to 9 ms |
| ON to OFF Response | 3 to 9 ms |
| Terminal Type (not included) | Removale 40-pin Connector' |
| Status Indicator | Module Activity LED |
| Weight | 2.1 oz. (60 g) |
| ${ }^{\text {Connector sold separately. } \text {. See Terminal }}$ Blocks and Wiring for wiring options. |  |





## Chapter 3: I/O Wiring and Specifications

## D2-32ND3-2, DC Input

| Inputs per Module | 32 (Sink/Source) |
| :---: | :---: |
| Commons per Module | 4 isolated (8 I/0 terminal points / com) |
| Input Voltage Range | 4.50 to 15.6 VDC min. to max. |
| Peak Voltage | 16 VDC |
| ON Voltage Level | 4 VDC minimum |
| OFF Voltage Level | 2 VDC maximum |
| AC Frequency | N/A |
| Input Impedance | $1.0 \mathrm{k} \Omega$ @ 5-15 VDC |
| Input Current | $\begin{aligned} & 4 \mathrm{~mA} @ 5 \mathrm{VDC} \\ & 11 \mathrm{~mA} \text { @ } 12 \mathrm{VDC} \\ & 14 \mathrm{~mA} \text { @ } 15 \mathrm{VDC} \end{aligned}$ |
| Maximum Input Current | 16 mA @ 15.6 VDC |
| Minimum ON Current | 3 mA |
| Maximum OFF Current | 0.5 mA |
| Base Power Required 5VDC | 25 mA |
| OFF to ON Response | 3 to 9 ms |
| ON to OFF Response | 3 to 9 ms |
| Terminal Type (not included) | Removable 40-pin connector ${ }^{1}$ |
| Status Indicator | Module activity LED |
| Weight | 2.10 O (60 g) |
| ${ }^{1}$ Connector sold separately. <br> See Terminal Blocks and Wiring for wiring options. |  |




Ambient T emperature (C/F)
Derating Chart
Input Voltage: 12VDC and 15VDC
Points


Chapter 3: I/O Wiring and Specifications

## D2-08NA-1, AC Input

| Inputs per Module | 8 |
| :--- | :--- |
| Commons per Module | $1(2 \mathrm{l} / 0$ terminal points) |
| Input Voltage Range | $80-132 \mathrm{VAC}$ |
| Peak Voltage | 132 VAC |
| ON Voltage Level | 75 VAC minimum |
| OFF Voltage Level | 20 VAC maximum |
| AC Frequency | $47-63 \mathrm{~Hz}$ |
| Input Impedance | $12 \mathrm{k} \mathrm{\Omega} @ 60 \mathrm{~Hz}$ |
| Input Current | $13 \mathrm{~mA} @ 100 \mathrm{VAC}, 60 \mathrm{~Hz}$ |
| Minimum ON Current | $11 \mathrm{~mA} @ 100 \mathrm{VAC}, 50 \mathrm{~Hz}$ |
| Maximum OFF Current | 5 mA |
| Base Power Required 5VDC | 2 mA |
| OFF to ON Response | 50 mA |
| ON to OFF Response | 5 to 30 ms |
| Terminal Type (included) | 10 to 50 ms |
| Status Indicator | Removable; D2-810CON |
| Weight | Logic side |
|  | $2.50 \mathrm{zz} .(70 \mathrm{~g})$ |





## Chapter 3: I/O Wiring and Specifications

## D2-08NA-2, AC Input

| Inputs per Module | 8 |
| :---: | :---: |
| Commons per Module | 1 (2 //0 terminal points) |
| Input Voltage Range | 170-265 VAC |
| Peak Voltage | 265 VAC |
| ON Voltage Level | 150 VAC minimum |
| OFF Voltage Level | 40 VAC maximum |
| AC Frequency | $47-63 \mathrm{~Hz}$ |
| Input Impedance | $18 \mathrm{k} \Omega$ @ 60 Hz |
| Input Current | 9 mA @ $220 \mathrm{VAC}, 50 \mathrm{~Hz}$ 11 mA @ $265 \mathrm{VAC}, 50 \mathrm{~Hz}$ 10 mA @ $220 \mathrm{VAC}, 60 \mathrm{~Hz}$ 12 mA @ $265 \mathrm{VAC}, 60 \mathrm{~Hz}$ |
| Minimum ON Current | 10 mA |
| Maximum OFF Current | 2 mA |
| Base Power Required 5VDC | 100 mA |
| OFF to ON Response | 5 to 30 ms |
| ON to OFF Response | 10 to 50 ms |
| Terminal Type (included) | Removable; D2-810CON |
| Status Indicator | Logic side |
| Weight | $2.502 .(70 \mathrm{~g})$ |


| Operating Temperature | $32^{\circ} \mathrm{F}$ to $131^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.55^{\circ} \mathrm{C}\right)$ |
| :--- | :--- |
| Storage Temperature | $-4^{\circ} \mathrm{F}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ} \mathrm{C}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Humidity | $35 \%$ to $95 \%$ (non-condensing) |
| Atmosphere | No corrosive gases permitted |
| Vibration | MIL STD 810 C 514.2 |
| Shock | MIL STD 810 C 516.2 |
| Insulation Withstand Voltage | 1,500 VAC 1 minute (COM-GND) |
| Insulation Resistance | $10 \mathrm{M} \simeq @ 500$ VDC |
| Noise Immunity | NEMA $1,500 \mathrm{~V} ~ 1 ~ m i n u t e ~$ <br> SANKI $1,000 \mathrm{~V} 1$ minute |
| RFI | $150 \mathrm{MHz}, 430 \mathrm{MHz}$ |




Chapter 3: I/O Wiring and Specifications

## D2-16NA, AC Input

| Inputs per Module | 16 |
| :--- | :--- |
| Commons per Module | 2 (isolated) |
| Input Voltage Range | $80-132 \mathrm{VAC}$ |
| Peak Voltage | 132 VAC |
| ON Voltage Level | 70 VAC minimum |
| OFF Voltage Level | 20 VAC maximum |
| AC Frequency | $47-63 \mathrm{~Hz}$ |
| Input Impedance | $12 \mathrm{k} \mathrm{\Omega}$ @ 60 Hz |
| Input Current | $11 \mathrm{~mA} @ 100 \mathrm{VAC}, 50 \mathrm{~Hz}$ |
|  | $13 \mathrm{~mA} @ 100 \mathrm{VAC}, 60 \mathrm{~Hz}$ |
|  | $15 \mathrm{~mA} @ 132 \mathrm{VAC}, 60 \mathrm{~Hz}$ |
| Minimum ON Current | 5 mA |
| Maximum OFF Current | 2 mA |
| Base Power Required 5VDC 100 mA |  |
| OFF to ON Response | 5 to 30 ms |
| ON to OFF Response | 10 to 50 ms |
| Terminal Type (included) | Removable; D2-16IOCON |
| Status Indicator | Logic side |
| Weight | $2.402 .(68 \mathrm{~g})$ |


| \|nputs per Module | 8 |
| :--- | :--- |
| Base Power Required 5VDC | 50 mA |
| Terminal Type | None |
| Status Indicator | Switch side |
| Weight | $2.65 \mathrm{oz} .(75 \mathrm{~g})$ |



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## Chapter 3: I/O Wiring and Specifications

## DL205 Digital Output Modules

D2-04TD1, DC Output

| Outputs per Module | 4 (current sinking) |
| :--- | :--- |
| Output Points Consumed | 8 points (only first 4 pts. used) |
| Commons per Module | 1 (4 I/0 terminal points) |
| Output Type | NMOS FET (open drain) |
| Operating Voltage | $10.2-26.4$ VDC |
| Peak Voltage | 40 VDC |
| ON Voltage Drop | 0.72 VDC maximum |
| AC Frequency | $\mathrm{N} / \mathrm{A}$ |
| Max Load Current | $4 \mathrm{~A} /$ /point |
| (resistive) | $8 \mathrm{~A} /$ common |
| Max Leakage Current | 0.1 mA @ 40 VDC |
| Max Inrush Current | 6 A for $100 \mathrm{~ms}, 15 \mathrm{~A}$ for 10 ms |
| Minimum Load Current | 50 mA |


| External DC Required | 24 VDC @ 20 mA max. |
| :--- | :--- |
| Base Power Required 5VDC 60 mA |  |
| OFF to ON Response | 1 ms |
| ON to OFF Response | 1 ms |
| Terminal Type (included) | Removable; D2-810coN |
| Status Indicator | Logic side |
| Weight | 2.8 oz. (80 g) |
| Fuses | $4(1$ per point) <br> (6.3 A slow blow, non-replaceable) |



| Inductive Load <br> Maximum Number of Switching Cycles per Minute |  |  |  |
| :---: | :---: | :---: | :---: |
| Load | Duration of output in ON state |  |  |
| Current | 7 ms | 40 ms | 100 ms |
| 0.1 A | 8000 | 1400 | 600 |
| 0.5A | 1600 | 300 | 120 |
| 1.0A | 800 | 140 | 60 |
| 1.5 A | 540 | 90 | 35 |
| 2.0A | 400 | 70 | - |
| 3.0A | 270 | - | - |
| 4.0A | 200 | - | - |

At 40 mS duration, loads of 3.0 A or greater cannot be used.
At 100 mS duration, loads of 2.0 A or greater cannot be used.
Find the load current you expect to use and the duration that the output is ON. The number at the intersection of the row and column represents the switching cycles per minute. For example, a 1 A inductive load that is on for 100 ms can be switched on and off a maximum of 60 times per minute. To convert this to duty cycle percentage use: (duration $\times$ cycles)/60. In this example, $(60 \times .1) / 60=.1$, or $10 \%$ duty cycle.


## D2-08TD1, DC Output

| Outputs per Module | 8 (current sinking) |
| :--- | :--- |
| Commons per Module | 1 (2 I/O terminal points) |
| Output Type | NPN open collector |
| Operating Voltage | $10.2-26.4$ VDC |
| Peak Voltage | 40 VDC |
| ON Voltage Drop | 1.5 VDC maximum |
| AC Frequency | N/A |
| Minimum Load Current | 0.5 mA |
| Max Load Current | $0.3 \mathrm{~A} / \mathrm{point}$ 2.4A/common |
| Max Leakage Current | 0.1 mA @ 40 VDC |
| Max Inrush Current | 1 A for 10 ms |
| Base Power Required 5VDC 100 mA |  |
| OFF to ON Response | 1 ms |
| ON to OFF Response | 1 ms |
| Terminal Type (included) | Removable; D2-810con |
| Status Indicator | Logic side |
| Weight | 2.3 oz. (65g) |
| Fuses | 1 per common |



## D2-08TD2, DC Output

| Outputs per Module | 8 (current sourcing) |
| :---: | :---: |
| Commons per Module | 1 |
| Output Type | PNP open collector |
| Operating Voltage | 12 to 24 VDC |
| Output Voltage | 10.8 to 26.4 VDC |
| Peak Voltage | 40 VDC |
| ON Voltage Drop | 1.5 VDC |
| AC Frequency | N/A |
| Minimum Load Current | N/A |
| Max Load Current | 0.3A per point; 2.4A per common |
| Max Leakage Current | 1.0 mA @ 40 VDC |
| Max Inrush Current | 1 A for 10 ms |
| Base Power Required 5VDC | 100 mA |
| OFF to ON Response | 1 ms |
| ON to OFF Response | 1 ms |
| Terminal Type (included) | Removable; D2-810CON |
| Status Indicator | Logic side |
| Weight | 2.1 oz. (60g) |
| Fuses | $\begin{aligned} & 1 \text { per common } \\ & 5 \text { A fast blow, non-replaceable } \end{aligned}$ |

## D2-16TD1-2, DC Output

| Outputs per Module | 16 (current sinking) |
| :---: | :---: |
| Commons per Module | 1 (2 //0 terminal points) |
| Output Type | NPN open collector |
| External DC required | $24 \mathrm{VDC} \pm 4 \mathrm{~V}$ @ 80 mA max |
| Operating Voltage | 10.2-26.4 VDC |
| Peak Voltage | 30 VDC |
| ON Voltage Drop | 0.5 VDC maximum |
| AC Frequency | N/A |
| Minimum Load Current | 0.2 mA |
| Max Load Current | $0.1 \mathrm{~A} /$ point 1.6A/common |
| Max Leakage Current | 0.1 mA @ 30 VDC |
| Max Inrush Current | 150 mA for 10 ms |
| Base Power Required 5VDC | 200 mA |
| OFF to ON Response | 0.5 ms |
| ON to OFF Response | 0.5 ms |
| Terminal Type (included) | Removable; D2-1610CON |
| Status Indicator | Logic side |
| Weight | 2.3 oz. (65g) |
| Fuses | None |



D2-16TD2-2, DC Output

| Outputs per Module | 16 (current sourcing) |
| :--- | :--- |
| Commons per Module | 2 |
| Output Type | NPN open collector |
| Operating Voltage | $10.2-26.4 \mathrm{VDC}$ |
| Peak Voltage | 30 VDC |
| ON Voltage Drop | 1.0 VDC maximum |
| AC Frequency | $\mathrm{N} / \mathrm{A}$ |
| Minimum Load Current | 0.2 mA |
| Max Load Current | $0.1 / /$ /point |
| Max Leakage Current | $1.6 \mathrm{~A} / \mathrm{module}$ |
| Max Inrush Current | 150 mA or 10 VDC |
| Base Power Required 5VDC 200 mA |  |
| OFF to ON Response | 0.5 ms |
| ON to OFF Response | 0.5 ms |
| Terminal Type (included) | Removable; D2-16lOCON |
| Status Indicator | Logic side |
| Weight | 2.8 oz ( 80 g ) |
| Fuses | None |



## F2-16TD1(2)P, DC Output With Fault Protection



NOTE: Not supported in D2-230, D2-240 and D2-250 CPUs.

These modules detect the following fault status and turn the related $\mathrm{X} \operatorname{bit}(\mathrm{s})$ on.

1. Missing external 24 VDC for the module
2. Open load ${ }^{1}$
3. Over temperature (the output is shut down)
4. Over load current (the output is shut down)

| Fault Status | X bit Fault Status Indication |
| :--- | :--- |
| Missing external 24VDC | All 16 X bits are on. |
| Open load ${ }^{1}$ | Only the $X$ bit assigned to the <br> faulted output is on |
| Over temperature |  |
| Over load current |  |

When these modules are installed, 16 X
bits are automatically assigned as the
fault status indicator. Each X bit
indicates the fault status of each output.
In this example, $\mathrm{X} 10-\mathrm{X} 27$ are assigned as the fault status indicator.
X10: Fault status indicator for Y 0
X11: Fault status indicator for Y1
$\nabla$
X26: Fault status indicator for Y16
X27: Fault status indicator for Y17
The fault status indicators (X bits) can be reset by performing the indicated operations in the

following table:

| Fault Status | Operation |
| :--- | :--- |
| Missing external 24VDC | Apply external 24VDC |
| Open load ${ }^{1}$ | Connect the load. |
| Over temperature | Turn the output (Y bit) off or |
| power cycle the PLC |  |

NOTE 1: Open load detection can be disabled by removing the jumper switch J6 on the module PC board.

Continued on next two pages.


## Chapter 3: I/O Wiring and Specifications

## F2-16TD1P, DC Output With Fault Protection



NOTE 3: This module does not currently support Think \& Do 8.0. It does not support Think \& Do Live! or Studio.

## F2-16TD2P, DC Output with Fault Protection

| Inputs per module | 16 (status indication) |
| :--- | :--- |
| Outputs per module | 16 (current sourcing) |
| Commons per module | 1 |
| Output type | NMOS FET (open source) |
| Operating voltage | 10.2 -26.4 VDC, external |
| Peak voltage | 40 VDC |
| AC frequency | $\mathrm{N} / \mathrm{A}$ |
| ON voltage drop | 0.7 V (output current 0.5 A ) |
| Overcurrent trip | 0.6 A min., 1.2A max. |
| Maximum load current | 0.25 A continuous, 0.5 A <br> peak |
| Maximum OFF current | Jumper J6 installed: $200 ~ \mu \mathrm{~A} ;$ <br> J6 removed: $30 ~ \mu \mathrm{~A}$ |
| Base power required 5V | 70 mA |
| OFF to ON response | 0.5 ms |
| ON to OFF response | 0.5 ms |
| Terminal type | Removable (D2-16IOCON) |
| Status indicators | Logic Side |
| Weight | 2.0 oz. (25g) |
| Fuses | None |
| External DC required | $24 \mathrm{VDC} \mathrm{+/-10} \mathrm{\%} \mathrm{@} 50 \mathrm{~mA}$ |
| External DC overvoltage | 27 VV , outputs are restored |
| when voltage is within limits |  |
| shutdown |  |



NOTE 1: Not supported in D2-230, D2-240 and D2-250 CPUs.

NOTE 2: Supporting Firmware: D2-250-1 must be V4.80 or later D2-260 must be V2.60 or later

NOTE 3: This module does not currently support Think \& Do 8.0. It does not support Think \& Do Live! or Studio.

## D2-32TD1, DC Output

| Outputs per Module | 32 (current sinking) |
| :--- | :--- |
| Commons per Module | 4 (8 I/0 terminal points) |
| Output Type | NPN open collector |
| Operating Voltage | $12-24 \mathrm{VDC}$ |
| Peak Voltage | 30 VDC |
| ON Voltage Drop | 0.5 VDC maximum |
| Minimum Load Current | 0.2 mA |
| Max Load Current | $0.1 \mathrm{~A} / \mathrm{point} ; 3.2 \mathrm{~A} \mathrm{per} \mathrm{module}$ |
| Max Leakage Current | 0.1 mA @ 30 VDC |
| Max Inrush Current | 150 mA for 10 ms |
| Base Power Required 5VDC | 350 mA |
| OFF to ON Response | 0.5 ms |
| ON to OFF Response | 0.5 ms |
| Terminal Type (not included) | removable 40-pin connector ${ }^{1}$ |
| Status Indicator | Module activity (no I/0 status |
| Weight | 2.1 oz. (60g) |
| Fuses | None |
| External DC Power Required | $20-28 \mathrm{VDC}$ max. 120 mA (all |
| points on) |  |



## D2-32TD2, DC Output

| Outputs per Module | 32 (current sourcing) |
| :--- | :--- |
| Commons per Module | 4 (8 I/0 terminal points) |
| Output Type | Transistor |
| Operating Voltage | 12 to 24 VDC |
| Peak Voltage | 30 VDC |
| ON Voltage Drop | 0.5 VDC @ 0.1 A |
| Minimum Load Current | 0.2 mA |
| Max Load Current | $0.1 \mathrm{~A} / \mathrm{point} ; ~ 0.8 \mathrm{~A} / \mathrm{common}$ |
| Max Leakage Current | 0.1 mA @ 30 VDC |
| Max Inrush Current | 150 mA @ 10 ms |
| Base Power Required 5VDC | 350 mA |
| OFF to ON Response | 0.5 ms |
| ON to OFF Response | 0.5 ms |
| Terminal Type (not included) | Removable 40-pin connector |
| Status Indicator | Module activity (no I/0 status |
| indicators) |  |



Chapter 3: I/O Wiring and Specifications

F2-08TA, AC Output

| Outputs per Module | 8 |
| :---: | :---: |
| Commons per Module | 2 (Isolated) |
| Output Type | SSR (Triac with zero crossover) |
| Operating Voltage | 24-140 VAC |
| Peak Voltage | 140 VAC |
| ON Voltage Drop | 1.6 V (rms) @ 1.5A |
| AC Frequency | 47 to 63 Hz |
| Minimum Load Current | 50 mA |
| Max Load Current | $\begin{aligned} & 1.5 \mathrm{~A} / \text { pt @ } @ 0^{\circ} \mathrm{C} \\ & 1.0 \mathrm{~A} / \mathrm{pt} \text { @ } 60^{\mathrm{C}} \mathrm{C} \\ & 4.0 \mathrm{~A} / \mathrm{common} ; 8.0 \mathrm{~A} / \text { module } \\ & @ 60^{\circ} \mathrm{C} \end{aligned}$ |
| Max Leakage Current | $0.7 \mathrm{~mA}(\mathrm{~ms})$ |
| Peak One Cycle Surge Current | 15A |
| Base Power Required 5VDC | 250 mA |
| OFF to ON Response | 0.5 ms - $1 / 2$ cycle |
| ON to OFF Response | 0.5 ms - $1 / 2$ cycle |
| Terminal Type (included) | Removable; D2-810CON |
| Status Indicator | Logic side |
| Weight | 3.502. |
| Fuses | None |



D2-08TA, AC Output

| Outputs per Module | 8 |
| :---: | :---: |
| Commons per Module | 1 (2 I/O terminal points) |
| Output Type | SSR (Triac) |
| Operating Voltage | 15-264 VAC |
| Peak Voltage | 264 VAC |
| ON Voltage Drop | $\begin{aligned} & <1.5 \mathrm{VAC}(>0.1 \mathrm{~A}) \\ & <3.0 \mathrm{VAC}(<0.1 \mathrm{~A}) \end{aligned}$ |
| AC Frequency | 47 to 63 Hz |
| Minimum Load Current | 10 mA |
| Max Load Current | 0.5A/point; 4A/common |
| Max Leakage Current | $\begin{aligned} & 4 \mathrm{~mA}(264 \mathrm{VAC}, 60 \mathrm{~Hz}) \\ & 1.2 \mathrm{~mA}(100 \mathrm{VAC}, 60 \mathrm{~Hz}) \\ & 0.9 \mathrm{~mA}(100 \mathrm{VAC}, 50 \mathrm{~Hz}) \end{aligned}$ |
| Max Inrush Current | 10A for 10 ms |
| Base Power Required 5VDC | 250 mA |
| OFF to ON Response | 1 ms |
| ON to OFF Response | $1 \mathrm{~ms}+1 / 2$ cycle |
| Terminal Type (included) | Removable; D2-810CON |
| Status Indicator | Logic side |
| Weight | 2.8 oz. (80g) |
| Fuses | 1 per common, 6.3A slow blow, non-replaceable |

## Chapter 3: I/O Wiring and Specifications

## D2-12TA, AC Output

3

| Outputs per Module | 12 |
| :--- | :--- |
| Outputs Points Consumed | 16 (four unused, see chart below) |
| Commons per Module | 2 (isolated) |
| Output Type | SSR (Triac) |
| Operating Voltage | $15-132 \mathrm{VAC}$ |
| Peak Voltage | 132 VAC |
| ON Voltage Drop | $<1.5 \mathrm{VAC}($ ( 50 mAA$)$ |
| AC Frequency | 44.0 VAC ( (50mA) |
| Minimum Load Current | 10 mA |
| Max Load Current | $0.3 \mathrm{~A} /$ /point; $1.8 \mathrm{~A} /$ common |


| Max Leakage Current | $2 \mathrm{~mA}(132 \mathrm{VAC}, 60 \mathrm{~Hz})$ |
| :--- | :--- |
| Max Inrush Current | 10 A for 10 ms |
| Base Power Required 5VDC | 350 mA |
| OFF to ON Response | 1 ms |
| ON to OFF Response | $1 \mathrm{~ms}+1 / 2$ cycle |
| Terminal Type (included) | Removable; D2-1610CON |
| Status Indicator | Logic side |
| Weight | 2.8 oz. (80g) |
| Fuses | (2) 1 per common <br> 3.15A slow blow, replaceable <br> Order D2-FUSE-1 (5 per pack) |



Chapter 3: I/O Wiring and Specifications

## D2-04TRS, Relay Output

| Outputs per Module | 4 |
| :--- | :--- |
| Outputs Points Consumed | 8 (only 1st 4pts. are used) |
| Commons per Module | 4 (isolated) |
| Output Type | Relay, form A (SPST) |
| Operating Voltage | $5-30 \mathrm{VDC} / 5-240 \mathrm{VAC}$ |
| Peak Voltage | $30 \mathrm{VDC}, 264 \mathrm{VAC}$ |
| ON Voltage Drop | 0.72 VDC maximum |
| AC Frequency | 47 to 63 Hz |
| Minimum Load Current | 10 mA |
| Max Load Current (resistive) | $4 \mathrm{~A} /$ point; $8 \mathrm{~A} /$ /odule (resistive) |


| Max Leakage Current | 0.1 mA @ 264 VAC |
| :--- | :--- |
| Max Inrush Current | 5 A for < 10 ms |
| Base Power Required 5VDC | 250 mA |
| OFF to ON Response | 10 ms |
| ON to OFF Response | 10 ms |
| Terminal Type (included) | Removable; D2-810CON |
| Status Indicator | Logic side |
| Weight | 2.8 oz. (80 g) |
| Fuses | 1 per point <br> 6.3A slow blow, replaceable <br> Order D2-FUSE-3 (5 per pack) |


| Typical Relay Life (Operations) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Voltage \& Load Current |  |  |  | A |
| 24 VDC Resistive 24 VDC Solenoid 110 VAC Resistive 110 VAC Solenoid 220 VAC Resistive 220 VAC Solenoid At 24 VDC, solen At 100 VAC, sole At 220 VAC, solen | $\begin{aligned} & 500 \mathrm{k} \\ & 100 \mathrm{k} \\ & 500 \mathrm{k} \\ & 200 \mathrm{k} \\ & 350 \mathrm{k} \\ & 100 \mathrm{k} \\ & \text { Iductive } \\ & \text { inductive } \\ & \text { inductive } \end{aligned}$ | $\begin{aligned} & 200 \mathrm{k} \\ & 40 \mathrm{k} \\ & 250 \mathrm{k} \\ & 100 \mathrm{k} \\ & 150 \mathrm{k} \\ & 50 \mathrm{k} \\ & \text { ds over } 2 \\ & \text { ads over } \\ & \text { ads over } \end{aligned}$ | 100 K <br> 150 k <br> 50 k <br> 100 K <br> -1 | 50k <br> -100 k <br> - <br> 50 k <br> - |





## Chapter 3: I/O Wiring and Specifications

## D2-08TR, Relay Output

| Outputs per Module | 8 |
| :--- | :--- |
| Outputs Points Consumed | 8 |
| Commons per Module | $1(2$ I/O terminals) |
| Output Type | Relay, form A (SPST) |
| Operating Voltage | $5-30$ VDC; $5-240$ VAC |
| Peak Voltage | $30 \mathrm{VDC}, 264 \mathrm{VAC}$ |
| ON Voltage Drop | $\mathrm{N} / \mathrm{A}$ |
| AC Frequency | 47 to 60 Hz |
| Minimum Load Current | 5 mA @ 5 VDC |
| Max Load Current (resistive) | 1A/point; 4A/common |


| Max Leakage Current | 0.1 mA @265 VAC |
| :--- | :--- |
| Max Inrush Current | Output: 3A for 10 ms |
| Common: 10 A for 10 ms |  |
| Base Power Required 5VDC | 250 mA |
| OFF to ON Response | 12 ms |
| ON to OFF Response | 10 ms |
| Terminal Type (included) | Removabl; D2-810C0N |
| Status Indicator | Logic side |
| Weight | 3.9 oz. (110g) |
| Fuses | One 6.3 A slow blow, replaceable <br> Order D2-FUSE-3 (5 per pack) |


| Typical Relay Life (Operations) |  |  |
| :--- | :---: | :---: |
| Voltaqe/Load | Current | Closures |
| 24 VDC Resistive | 1 A | 500 k |
| 24 VDC Solenoid | 1 A | 100 k |
| 110 VDC Resistive | 1 A | 500 k |
| 110 VCC Solenoid | 1 A | 200 k |
| 220 VAC Resistive | 1 A | 350 k |
| 220 VAC Solenoid | 1 A | 100 k |





Chapter 3: I/O Wiring and Specifications

## F2-08TR, Relay Output

| Outputs per Module | 8 |
| :---: | :---: |
| Outputs Points Consumed | 8 |
| Commons per Module | 2 (isolated), 4-pts. per common |
| Output Type | 8, Form A (SPST normally open) |
| Operating Voltage | $\begin{aligned} & \text { 7A @ 12-28 VDC, 12-250VAC; } \\ & 0.5 \mathrm{~A} @ 120 \text { VDC } \end{aligned}$ |
| Peak Voltage | $150 \mathrm{VDC}, 265 \mathrm{VAC}$ |
| ON Voltage Drop | N/A |
| AC Frequency | 47 to 63Hz |
| Minimum Load Current | 10 mA @ 12 VDC |
| Max Load Current (resistive) | 10A/point ${ }^{3}$ (subject to derating) Max of 10A/common |
| Max Leakage Current | N/A |
| Max Inrush Current | 12A |
| Base Power Required 5VDC | 670 mA |
| OFF to ON Response | $15 \mathrm{~ms}($ typical) |
| ON to OFF Response | 5 ms (typical) |
| Terminal Type (included) | Removable; D2-810CON |
| Status Indicator | Logic side |
| Weight | 5.5 oz. (156g) |
| Fuses | None |


| Typical Relay Life ${ }^{1}$ (Operations) at Room Temperature |  |  |  |
| :---: | :---: | :---: | :---: |
| Voltage \& |  |  |  |
| Type of Load ${ }^{2}$ | Load Current |  |  |
|  | 50mA | 5A | 7A |
| 24 VDC Resistive | 10M | 600k | 300k |
| 24 VDC Solenoid | - | 150k | 75k |
| 110 VDC Resistive | - | 600k | 300k |
| 110 VDC Solenoid | - | 500k | 200k |
| 220 VAC Resistive | - | 300k | 150k |
| 220 VAC Solenoid | - | 250k | 100k |
| 1) Contact life may be extended beyond those values shown with the |  |  |  |
| use of arc suppression techniques described in the DL205 User |  |  |  |
| Manual. Since these modules have no leakage current, they do not have built-in snubber. For example, if you place a diode across a |  |  |  |
| 24 VDC inductive Ioad, you can significantly increase the life of the relay. |  |  |  |
| 2) At 120 VDC 0.5A resistive load, contact life cycle is 200k cycles. |  |  |  |
| 3) Normally closed contacts have $1 / 2$ the current handling capability of the normally open contacts. |  |  |  |



## Chapter 3: I/O Wiring and Specifications

## F2-08TRS, Relay Output

| Outputs per Module | 8 |
| :---: | :---: |
| Outputs Points Consumed | 8 |
| Commons per Module | 8 (isolated) |
| Output Type | 3, Form C (SPDT) 5, Form A (SPST normally open) |
| Operating Voltage | $\begin{aligned} & \text { 7A @ 12-28 VDC, 12-250 VAC } \\ & 0.5 \mathrm{~A} @ 120 \mathrm{VDC} \end{aligned}$ |
| Peak Voltage | 150 VDC, 265 VAC |
| ON Voltage Drop | N/A |
| AC Frequency | 47 to 63Hz |
| Minimum Load Current | 10 mA @ 12 VDC |
| Max Load Current (resistive) | 7A/point ${ }^{3}$ (subject to derating) |
| Max Leakage Current | N/A |
| Max Inrush Current | 12A |
| Base Power Required 5VDC | 670 mA |
| OFF to ON Response | 15 ms (typical) |
| ON to OFF Response | 5 ms (typical) |
| Terminal Type (included) | Removable; D2-16IOCON |
| Status Indicator | Logic side |
| Weight | 5.50z. (156g) |
| Fuses | None |


| Typical Relay Life ${ }^{\mathbf{1}}$ |  |  |  |
| :--- | :--- | :--- | :--- |
| Temperature |  |  |  |

1) Contact life may be extended beyond those values shown with the use of arc suppression techniques described in the DL205 User Manual. Since these modules have no leakage current, they do not have built-in snubber. For example, if you place a diode across a 24 VDC inductive load, you can significantly increase the life of the relay.
2) At 120 VDC 0.5A resistive load, contact life cycle is 200k cycles.
3) Normally closed contacts have $1 / 2$ the current handling capability of the normally open contacts.


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Chapter 3: I/O Wiring and Specifications

## D2-12TR, Relay Output

| Outputs per Module | 12 | Typical Relay Life (Operations) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Outputs Points Consumed | 16 (four unused, see chart below) | Voltage/Load |  | Current | Closures |
| Commons per Module | 2 (6-pts. per common) | 24 VDC Resistive |  | 1 A1 A | 500k |
| Output Type | Relay, form A (SPST) | 24 VD |  |  | 100k |
| Operating Voltage | 5-30 VDC; 5-240 VAC |  | istive | 1 A | 500 k |
| Peak Voltage | $30 \mathrm{VDC} ; 264 \mathrm{VAC}$ |  |  | 1 A | 200k |
| ON Voltage Drop | N/A |  |  | $1 \mathrm{~A}$ | 350k |
| AC Frequency | 47 to 60 Hz |  |  |  |  |
| Minimum Load Current | 5 mA @ 5VDC |  |  |  |  |
| Max Load Current (resistive) | $1.5 \mathrm{~A} / \mathrm{point}$; Max of $3 \mathrm{~A} /$ common |  |  | es Used |  |
| Max Leakage Current | 0.1 mA @ 265 VAC | Points | Used? | Points | Used? |
| Max Inrush Current | Output: 3A for 10 ms Common: 10A for 10 ms | Yn+0 | Yes | Yn+10 | Yes |
| Base Power Required 5VDC | 450 mA | $Y_{n+1}$ | Yes | Yn+11 | Yes |
| OFF to ON Response | 10 ms | Yn+2 | Yes | $Y_{n+12}$ | Yes |
| ON to OFF Response | 10 ms | Yn+3 | Yes | $Y_{n+13}$ | Yes |
| Terminal Type (included) | Removable; D2-1610CON | Yn+4 | Yes | $Y_{n+14}$ | Yes |
| Status Indicator | Logic side | Yn+5 | Yes | $\mathrm{Y}_{\mathrm{n}+15}$ | Yes |
| Weight | 4.6 oz. (130g) | Yn+6 | No | $Y_{n+16}$ | No |
| Fuses | (2) 4A slow blow, replaceable | Yn+7 | No | $Y_{n+17}$ | No |
| Fuses | Order D2-FUSE-4 (5 per pack) |  |  | ting address |  |



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## Chapter 3: I/O Wiring and Specifications

## D2-08CDR, 4 pt. DC Input / 4pt. Relay Output

| General Specifications |  |
| :--- | :--- |
| Base Power Required 5VDC 200 mA |  |
| Terminal Type (included) | Removabl; D2-810CON |
| Status Indicator | Logic side |
| Weight | 3.5 oz. (100 g) |
| Input Specifications |  |
| Inputs per Module | 4 (sink/source) |
| Input Points Consumed | 8 (only first 4-pts. are used) |
| Commons per Module | 1 |
| Input Voltage Range | $20-28$ VDC |
| Peak Voltage | 30 VDC |
| ON Voltage Level | 19 VDC minimum |
| OFF Voltage Level | 7 VDC maximum |
| AC Frequency | $\mathrm{N} / \mathrm{A}$ |
| Input Impedance | $4.7 \mathrm{k} \mathrm{\Omega}$ |
| Input Current | $5 \mathrm{~mA} @ 24 \mathrm{VDC}$ |
| Maximum Current | 8 mA @ 30 VDC |
| Minimum ON Current | 4.5 mA |
| Maximum OFF Current | 1.5 mA |
| OFF to ON Response | 1 to 10 ms |
| ON to OFF Response | 1 to 10 ms |
| Fuses (input circuits) | None |


| Typical Relay Life (Operations) |  |  |
| :--- | :---: | :---: |
| Voltage/Load | Current | Closures |
| 24 VDC Resistive | 1 A | 500 k |
| 24 VDC Solenoid | 1 A | 100 k |
| 10 VDC Resisive | 1 A | 50 k |
| 110 VDC Solenoid | 1 A | 20 k |
| 220 VAC Resistive | 1 A | 350 k |
| 220 VAC Solenoid | 1A | 100 k |


| Output Specifications |  |
| :---: | :---: |
| Outputs per Module | 4 |
| Outputs Points Consumed | 8 (only first 4-pts. are used) |
| Commons per Module | 1 |
| Output Type | Relay, form A (SPST) |
| Operating Voltage | 5-30 VDC; 5-240 VAC |
| Peak Voltage | $30 \mathrm{VDC} ; 264 \mathrm{VAC}$ |
| ON Voltage Drop | N/A |
| AC Frequency | 47 to 63 Hz |
| Minimum Load Current | 5 mA @ 5 VDC |
| Max Load Current (resistive) | 1A/point; 4A/module |
| Max Leakage Current | 0.1 mA @ 264 VAC |
| Max Inrush Current | 3A for < 100 ms 10 A for < 10 ms (common) |
| OFF to ON Response | 12 ms |
| ON to OFF Response | 10 ms |
| Fuses (output circuits) | 1 (6.3A slow blow, replaceable); Order D2-FUSE-3 (5 per pack) |



## Chapter 3: I/O Wiring and Specifications

## NOTES:

## Chapter 3: I/O Wiring and Specifications

## DL205 Analog Input Modules

F2-04AD-1 4-Channel 4-20mA Analog Input Module

| This module can be powered by either a 12 VDC or 24 VDC power supply, and is a direct <br> replacement for F2-04AD-1L modules. |  |
| :--- | :--- |
| Number of Channels | 4 , single ended (1 common) |
| Input Ranges | 4 to 20 mA current |
| Resolution | 12 -bit (1 in 4096) |
| Active Low-pass Filtering | -3 dB at $120 \mathrm{~Hz}, 2$ poles |
| $(-12 \mathrm{~dB}$ per octave) |  |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## F2-04AD-1 4-Channel 4-20mA Analog Input



Note 1: Shields should be grounded at the signal source
More than one external power supply can be used provided all the power supply commons are connected. A Series 217, 0.032A, fast-acting fuse is recommended for
4-20 mA current loops. If the power supply common of an external power supply is not connected to OVDC on the module, then the output of the external transmitter
must be isolated. To avoid "ground loop" errors, recommended 4-20 mA transmitter types are:
2 or 3 wire: Isolation between input signal and power supply.
4 wire: Isolation between input signal, power supply, and 4-20 mA output

## Chapter 3: I/O Wiring and Specifications

## F2-08AD-1 8-Channel 4-20mA Analog Input Module

| Number of Channels | 8, single ended (1 common) |
| :---: | :---: |
| Input Ranges | 4 to 20 mA current |
| Resolution | 12 bit (1 in 4096) |
| Low-pass Filtering | -3 dB at 200 Hz, (-6dB per octave) |
| Input Impedance | $250 \Omega \pm 0.1 \%, 1 / 2 \mathrm{~W}$ current input |
| Absolute Maximum Ratings | -45 mA to +45 mA |
| Converter Type | Successive approximation |
| Conversion Time (PLC Update Rate) | (D2-230 CPU) 1 channel per scan maximum (D2-240, D2-250(-1) and D2-260 CPUs) 8 channels per scan maximum |
| Linearity Error (End to End) | $\pm 1$ count (0.025\% of full scale) maximum |
| Input Stability | $\pm 1$ count |
| Full Scale Calibration Error (offset error not included) | $\pm 5$ counts max., @ 20 mA current input |
| Offset Calibration Error | $\pm 2$ counts max., @ 4mA current input |
| Step Response | $1 \mathrm{msto} 95 \%$ of F.S. change |
| Maximum Inaccuracy | $\begin{aligned} & \pm .1 \% @ 77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right) \\ & \pm .25 \% 32^{\circ} \text { to } 140^{\circ} \mathrm{F}\left(0^{\circ} \text { to } 60^{\circ} \mathrm{C}\right) \end{aligned}$ |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum full scale (including max. offset change of two counts) |
| Recommended Fuse | 0.032A, Series 217 fast-acting, current inputs |
| Digital Input Points Required | 16 (X) input points <br> (12 binary data bits, 3 channel ID bits, 1 broken transmitter bit) |
| Base Power Required 5VDC | 100 mA |
| External Power Supply | 5 mA maximum, +10 to +30 VDC |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $60^{\circ} \mathrm{C}$ ) |
| Storage Temperature | $-4^{\circ}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## F2-08AD-1 8-Channel 4-20mA Analog Input



Note 1: Shields should be grounded at the signal source.
More than one external power supply can be used provided all the power supply commons are connected. A Series 217, 0.032A, fastacting fuse is recommended for $4-20 \mathrm{~mA}$ current loops. If the power supply common of an external power supply is not connected to 0 VDC on the module, then the output of the external transmitter must be isolated. To avoid "ground loop" errors, recommended 4-20 mA transmitter types are:

2 or 3 wire: Isolation between input signal and power supply.
4 wire: Isolation between input signal, power supply, and 4-20 mA output

F2-04AD-2 4-Channel Voltage Analog Input Module

| This module can be powered by either a 12 VDC or 24 VDC power supply, and is a direct replacement for F2-04AD-2L modules. |  |
| :---: | :---: |
| Number of Channels | 4, single ended (1 common) |
| Input Ranges | 0 to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$ |
| Resolution | 12 bit (1 in 4096) |
| Active Low-pass Filtering | -3 dB at $80 \mathrm{~Hz}, 2$ poles (-12 dB per octave) |
| Input Impedance | $>20 \mathrm{M} \Omega$ |
| Absolute Maximum Ratings | -75 to +75 VDC |
| Converter Type | Successive approximation |
| Conversion Time (PLC Update Rate) | 1 channel per scan maximum (D2-230 CPU) 4 channels per scan maximum (D2-240, D2-250(-1) and D2-260 CPUs) |
| Linearity Error (End to End) | $\pm 1$ count ( $0.025 \%$ of full scale) maximum $\pm 2$ counts maximum (bi-polar) |
| Input Stability | $\pm 1$ count |
| Full Scale Calibration Error (offset error not included) | $\pm 3$ counts maximum |
| Offset Calibration Error | $\pm 1$ count maximum (0V input) |
| Maximum Inaccuracy | $\begin{aligned} & \pm .1 \% @ 77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right) \\ & \pm .3 \% 32^{\circ} \text { o } 140^{\circ} \mathrm{F}\left(0^{\circ} \text { to } 60^{\circ} \mathrm{C}\right) \end{aligned}$ |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ full scale calibration change (including maximum offset change ) |
| Digital Input Points Required | 16(x) input points <br> (12 binary data bits, 2 channel ID bits) |
| Base Power Required 5VDC | 110 mA |
| External Power Supply | 5 mA maximum, +10 to +30 VDC |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0\right.$ to $60^{\circ} \mathrm{C}$ ) |
| Storage Temperature | $-4^{0}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-8IOCON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## F2-04AD-2 4-Channel Voltage Analog Input



Note 1: Shields should be grounded at the signal source.

## F2-08AD-2 8-Channel Voltage Analog Input Module

| Number of Channels | 8, single ended (1 common) |
| :--- | :--- |
| Input Ranges | 0 to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{VDC}$ |
| Resolution | 12 bit (1 in 4095$)$ uni-polar <br> 13 bit ( -4095 to 4095) bi-polar |
| Active Low-pass Filtering | -3 dB at 200 Hz, |
| $(-6 \mathrm{~dB}$ per octave) |  |$|$| Input Impedance | $>20 \mathrm{M} \Omega$ |
| :--- | :--- |
| Absolute Maximum Ratings | -75 to +75 VDC |
| Converter Type | Successive approximation |
| Conversion Time (PLC | 1 channel per scan maximum (D2-230 CPU) <br> 8 channels per scan maximum (D2-240, <br> D2-250(-1) and D2-260 CPUs) |
| Update Rate) | $\pm 1$ count (0.025\% of full scale) maximum |
| Input Stability | $\pm 1$ count |
| Full Scale Calibration Error |  |
| (offset error not included) | $\pm 3$ counts maximum |
| Offset Calibration Error | $\pm 1$ count maximum (0V input) |
| Step Response | 1 ms to $95 \%$ of F.S. change |


| Maximum Inaccuracy | $\pm .1 \% ~ @ ~$ <br> $\pm 7^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ <br> $\pm .3 \% 32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ |
| :--- | :--- |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum full scale <br> (including max. offset change of 2 counts) |
| Digital Input Points Required | 16 ( X ) input points, <br> $(12$ binary data bits, 3 channel ID bits, 1 sign bit, <br> 1 diagnostic bit) |
| Base Power Required 5VDC | 100 mA |
| External Power Supply | 5 mA maximum, +10 to +30 VDC |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ |
| Storage Temperature | $-4^{\circ}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5 to $95 \%$ (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810 C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096). Includes circuitry to automatically detect broken or open transmitters.

## F2-08AD-2 8-Channel Voltage Analog Input



Note 1: Shields should be grounded at the signal source.
Note 2: Connect all external power supply commons.
Note 3: Connect unused channels (CH5+, CH6+, CH7+, CH8+ in this example) to OVDC.

## Chapter 3: I/O Wiring and Specifications

## DL205 RTD and Thermocouple Modules

## F2-04RTD 4-Channel RTD Input Module

| Number of Channels | 4 |
| :--- | :--- |
|  | Type Pt100: $-200.0 / 850.0^{\circ} \mathrm{C}$, <br> $-328 / 1562^{\circ} \mathrm{F}$ <br> Type Pt1000: $-200.0 / 595.0^{\circ} \mathrm{C}$, <br> Input Ranges <br> $-328 / 103^{\circ} \mathrm{F}$ <br> Type jPt100: $-38.0 / 450.0^{\circ} \mathrm{C}$, <br> $-36 / 842^{\circ} \mathrm{F}$ <br> Type CU-10/25z: $-200.0 / 260.0^{\circ} \mathrm{C}$, <br> $-328 / 500^{\circ} \mathrm{F}$ |
| Resolution | 16 bit $(1$ in 65535$)$ |
| Display Resolution | $\pm 0.1^{\circ} \mathrm{C}, \pm 0.1^{\circ} \mathrm{F}( \pm 3276.7)$ |
| RTD Excitation Current | $200 \mu \mathrm{~A}$ |
| Input Type | Differential |
| Notch Filter | $>100 \mathrm{db}$ notches at $50 / 60 \mathrm{~Hz}$ |
| Maximum Setting Time | $-3 \mathrm{db}=13.1 \mathrm{~Hz}$ |
| Coms (full-scale step input) |  |
| Absolute Maximum | $0-5 \mathrm{VDC}$ |
| Ratings | Fault protected inputs to $\pm 50 \mathrm{VDC}$ |
| Sampling Rate | 160 ms per channel |


| Converter Type | Charge Balancing |
| :--- | :--- |
| Linearity Error | $\pm .05^{\circ} \mathrm{C}$ maximum, $\pm .01^{\circ} \mathrm{C}$ typical |
| Maximum Inaccuracy | $\pm 1^{\circ} \mathrm{C}$ |
| PLC Update Rate | 4 channel/scan max., 240/250(-1)/D2-260CPUs <br> 1 channel per scan max., 230 CPU |
| Digital Input Points Required | 32 input points (16 binary data bits, <br> 2 channel ID bits, 4 fault bits) |
| Base Power Required 5VDC | 90 mA |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ |
| Storage Temperature | $-4^{\circ}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Temperature Drift | None (self-calibrating) |
| Relative Humidity | 5 to $95 \%$ (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810 C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-8IOCON |

## F2-04RTD 4-Channel RTD Input

Note 1


## Notes:

1. The three wires connecting the RTD to the module must be the same type and length. Do not use the shield or drain wire for the third connection.
2. If an RTD sensor has four wires, the plus sense wire should be left unconnected as shown.
3. This module is not compatible with the ZIPLink wiring systems.

## F2-04THM 4-Channel Thermocouple Input Module

| Number of Channels | 4, differential |
| :---: | :---: |
| Common Mode Range | $\pm 5 \mathrm{VDC}$ |
| Common Mode Rejection | 90 dB min. @ DC, 150 dB min. @ 50/60 Hz. |
| Input Impedance | $1 \mathrm{M} \Omega$ |
| Absolute Maximum Ratings | Fault-protected inputs to $\pm 50$ VDC |
| Accuracy vs. Temperature | $\pm 5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ maximum full scale calibration (including maximum offset change) |
| PLC Update Rate | 4 channels per scan max. D2-240/250(-1)/D2-260 CPU, H2-EBC(-F); 1 chan. per scan max. D2-230 CPU |
| Digital Input Points Required | 32 (X) input points (16 binary data bits, 2 channel ID bits, 4 diagnostic bits) |
| External Power Supply | 60 mA maximum, 18 to 26.4 VDC |
| Base Power Required 5VDC | 110 mA |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ |
| Storage Temperature | $-4^{0}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Non-removable |


| CPU Firmware Required |  |
| :--- | :--- |
| CPU | Firmware Required |
| D2-230 | V1.06 |
| D2-240 | V2.5 |
| D2-250 | V1.06 |
| D2-250-1, $\mathbf{D 2 - 2 6 0 ~}$ | All firmware versions work |

Notes:
1: Terminate shields at the respective signal source.
2. Connect unused channels to a common terminal (OV, CH4+, CH4).

3: When using 0-156 mV and 5V ranges, connect (-) or (0) volts terminal to OV to ensure common mode range acceptance.
4. This module is not compatible with the ZIPLink wiring system.

Chapter 3: I/O Wiring and Specifications

## F2-04THM 4-Channel Thermocouple Input

| Input Ranges | Type J -190 to $760^{\circ} \mathrm{C}$ Type E-210 to $1000^{\circ} \mathrm{C}$ Type K -150 to $1372^{\circ} \mathrm{C}$ Type R 65 to $1768^{\circ} \mathrm{C}$ Type S 65 to $1768^{\circ} \mathrm{C}$ Type T-230 to $400^{\circ} \mathrm{C}$ Type B 529 to $1820^{\circ} \mathrm{C}$ Type $\mathrm{N}-70$ to $1300^{\circ} \mathrm{C}$ Type C 65 to $2320^{\circ} \mathrm{C}$ | -310 to $1400^{\circ} \mathrm{F}$ -346 to $1832^{\circ} \mathrm{F}$ -238 to $2502^{\circ} \mathrm{F}$ 149 to $3214^{\circ} \mathrm{F}$ 149 to $3214^{\circ} \mathrm{F}$ -382 to $752^{\circ} \mathrm{F}$ 984 to $3308^{\circ} \mathrm{F}$ -94 to $2372^{\circ} \mathrm{F}$ 149 to $4208^{\circ} \mathrm{F}$ |
| :---: | :---: | :---: |
| Display Resolution | $\pm 0.1^{\circ} \mathrm{Cor} \pm 0.1^{\circ} \mathrm{F}$ |  |
| Cold Junction Compensation | Automatic |  |
| Conversion Time | 100 ms per channel |  |
| Warm-Up Time | 30 minutes typically $\pm \pm^{\circ} \mathrm{C}$ repeatability |  |
| Linearity Error (End to End) | $\pm .05^{\circ} \mathrm{C}$ maximum, $\pm .01^{\circ} \mathrm{C}$ typical |  |
| Maximum Inaccuracy | $\pm 3^{3} \mathrm{C}$ (excluding thermocouple error) |  |
| Voltage Input Specifications |  |  |
| Voltage Ranges | $0-5 \mathrm{~V}, \pm 5 \mathrm{~V}, 0-156.25 \mathrm{mV}, \pm 156.25 \mathrm{mVDC}$ |  |
| Resolution | 16 bit (1 in 65535) |  |
| Full Scale Calibration Error (Offset Error Included) | $\pm 13$ counts typical $\pm 33$ maximum |  |
| Offset Calibration Error | $\pm 1$ count maximum, @ OV input |  |
| Linearity Error (End to End) | $\pm 1$ count maximum |  |
| Maximum Inaccuracy | $\pm .02 \%$ @ $25^{\circ} \mathrm{C}$ (770\%) |  |



## Chapter 3: I/O Wiring and Specifications

## DL205 Analog Output Modules

## F2-02DA-1 2-Channel 4-20mA Analog Output Module

| This module requires a 24 VDC user power supply for operation. See the F2-02DA-1L on the next page if you want to use a 12 VDC supply. All other specifications are the same. |  |
| :---: | :---: |
| Number of Channels | 2 |
| Output Ranges | 4 to 20 mA |
| Resolution | 12 bit (1 in 4096) |
| Output Type | Single ended, one common |
| Digital Output Points Required | 16 (Y) output points (12 binary data bits, 2 channel ID bits) |
| Maximum Loop Supply | 30 VDC |
| Peak Output Voltage | 40 VDC <br> (clamped by transient voltage suppressor) |
| Load Impedance | $0 \Omega$ minimum |
| Maximum Load/Power Supply | $620 \Omega / 18 \mathrm{~V}, 910 \Omega / 24 \mathrm{~V}, 1200 \Omega / 30 \mathrm{~V}$ |
| PLC Update Rate | 1 channel per scan maximum D2-230 CPU <br> 2 channels per scan maximum (D2-240, <br> D2-250(-1) and D2-260 CPUs) |
| Linearity Error (end to end) | $\pm 1$ count ( $\pm 0.025 \%$ of full scale) maximum |
| Conversion Settling Time | 100 us maximum (full scale change) |
| Full Scale Calibration Error (offset error included) | $\pm 5$ counts max., 20 mA @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Offset Calibration Error | $\pm 3$ counts max., 4 mA @ 77 ${ }^{\circ}$ ( $25 C^{\circ}$ ) |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ full scale calibration change (including maximum offset change of 2 counts) |
| Maximum Inaccuracy | $\begin{aligned} & 0.1 \% @ 77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right) \\ & 0.3 \% \text { @ } 32^{\circ} \mathrm{t} 140^{\circ} \mathrm{F}\left(0^{\circ} \text { to } 60^{\circ} \mathrm{C}\right) \end{aligned}$ |
| Base Power Required 5VDC | 40 mA |
| External Power Supply | 18 to $30 \mathrm{VDC}, 60 \mathrm{~mA}$. (add 20 mA for each current loop used) |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $60^{\circ} \mathrm{C}$ ) |
| Storage Temperature | -4 to $158^{\circ} \mathrm{F}\left(-20\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5\% to 95\% (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## F2-02DA-1 2-Channel 4-20mA Analog Output



NOTE 1: Shields should be connected to the OV of the module or the OV of the R/S.
NOTE 2: Unused current outputs should remain open (no connections) for minimum power consumption.

## F2-02DA-1L 2-Channel 4-20mA Analog Output Module

| This module requires a 12 VDC user power supply for operation. See the F2-02DA-1 on the previous page if you want to use a 24 VDC supply. All other specifications are the same. |  |
| :---: | :---: |
| Number of Channels | 2 |
| Output Ranges | 4 to 20 mA |
| Resolution | 12 bit (1 in 4096) |
| Output Type | Single ended, 1 common |
| Digital Output Points Required | 16(Y) output points <br> (12 binary data bits, 2 channel ID bits) |
| Maximum Loop Supply | 30 VDC |
| Peak Output Voltage | 40 VDC <br> (clamped by transient voltage suppressor) |
| Load Impedance | $0 \Omega$ minimum |
| Maximum Load/Power Supply | 620 $/ 18 \mathrm{~V}, 910 \Omega / 24 \mathrm{~V}, 1200 \Omega / 30 \mathrm{~V}$ |
| PLC Update Rate | 1 channel per scan maximum (D2-230 CPU) 2 channels per scan maximum (D2-240, D2-250(-1) and D2-260 CPUs) |
| Linearity Error (end to end) | $\pm 1$ count ( $0.025 \%$ of full scale) maximum |
| Conversion Settling Time | $100 \mu \mathrm{~s}$ maximum (full scale change) |
| Full Scale Calibration Error (offset error included) | $\pm 5$ counts max., $20 \mathrm{~mA} @ 77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Offset Calibration Error | $\pm 3$ counts max., 4mA @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ full scale calibration change (including maximum offset change of 2 counts) |
| Maximum Inaccuracy | $\begin{aligned} & +0.1 \% \text { @ } 77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right) \\ & \pm 0.3 \% \text { @ } 32 \text { to } 140^{\circ} \mathrm{F}\left(0 \text { to } 60^{\circ} \mathrm{C}\right) \end{aligned}$ |
| Base Power Required 5VDC | 40 mA |
| External Power Supply | 10 to 15 VDC, 70 mA (add 20 mA for each current loop used) |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $60^{\circ} \mathrm{C}$ ) |
| Storage Temperature | $-4^{0}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## F2-02DA-1L 2-Channel 4-20mA Analog Output



NOTE 1: Shields should be connected to the OV of the module or the OV of the P/S.
NOTE 2: Unused current outputs should remain open (no connections) for minimum power consumption.
Maximum user load is dependent upon loop power supply.

| Loop power supply | Load range (ohm) |
| :--- | :--- |
| 15 VDC | 0 to 450 |
| 12 VDC | 0 to 300 |
| 10 VDC | 0 to 200 |

## F2-02DAS-1 2-Channel Isolated 4-20mA Analog Output Module

| Number of Channels | 2, isolated |
| :---: | :---: |
| Output Ranges | 4 to 20 mA |
| Resolution | 16 bit (1 in 65536) |
| Output Type | Current sourcing |
| Digital Output Points Required | 32 (Y) output points <br> (16 binary data bits, 2 channel ID bits, 1 output enable bit) |
| Isolation Voltage | $\pm 750 \mathrm{~V}$ continuous, channel to channel, channel to logic |
| Base Power Required 5VDC | 100 mA |
| Loop Supply | 18-32 VDC |
| External Power Supply | 18-32 VDC @ 50 mA per channel |
| Output Loop Compliance | Vin -2.5V |
| Load Impedance | 0-1375 $\Omega$ (@ 32 V ) |
| Maximum Load/ Power Supply | $375 \Omega / 12 \mathrm{~V}, 975 \Omega / 24 \mathrm{~V}, 1375 \Omega / 32 \mathrm{~V}$ |
| PLC Update Rate | 1 channel per scan maximum (D2-230 CPU) <br> 2 channels per scan maximum (D2-240, <br> D2-250(-1) and D2-260 CPUs) |
| Conversion Settling Time | $3 \mathrm{~ms} \mathrm{to} 0.1 \%$ of full scale |
| Linearity Error (end to end) | $\pm 10$ count ( $\pm 0.015 \%$ of full scale) maximum |
| Gain Calibration Error | $\pm 32$ counts ( $\pm 0.05 \%$ ) |
| Offset Calibration Error | $\pm 13$ counts ( $\pm 0.02 \%$ ) |
| Output Drift | $50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |
| Maximum Inaccuracy | $0.07 \%$ @ $25^{\circ} \mathrm{C}$ ( $77^{\circ} \mathrm{F}$ ) $0.18 \% 0$ to $60^{\circ} \mathrm{C}$ ( $32^{\circ}$ to $140^{\circ} \mathrm{F}$ ) |
| Operating Temperature | $0^{\circ}$ to $60^{\circ} \mathrm{C}\left(32^{\circ}\right.$ to 140 $\left.{ }^{\circ} \mathrm{F}\right)$ |
| Storage Temperature | $-20^{\circ}$ to $70^{\circ} \mathrm{C}\left(-4^{\text {a }}\right.$ to $\left.158^{\circ} \mathrm{F}\right)$ |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810 C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 65536).

## F2-02DAS-1 2-Channel Isolated 4-20mA Analog Output



ONOTE 1: Shields should be connected to the OV terminal of the module.
NOTE 2: Load must be within compliance voltage.
NOTE 3: For non-isolated outputs, connect all OV's together (0V1...OV2) and connect all +V's together (+V1...+V2).

## F2-08DA-1 8-Channel 4-20mA Analog Output Module

| Number of Channels | 8 , single-ended |
| :--- | :--- |
| Output Ranges | 4 to 20 mA |
| Resolution | 12 bit (1 in 4096) |
| Output Type | Current sinking or current sourcing |
| Digital Output Points <br> Required | 16 (Y) output points <br> $(12$ binary data bits, 3 channel ID bits, 1 output <br> enable bit) |
| Base Power Required 5VDC | 30 mA |
| Maximum Loop Voltage | 30 VDC |
| External Power Supply | 18 to $30 \mathrm{VDC}, 50 \mathrm{~mA} .$, class 2 <br> (add 20 mA for each current loop used) |
| Source Load | $0-400 \Omega$ @ 18-30 VDC |
| Sink Load | $0-600 \Omega / 18 \mathrm{~V}, 0-900 \Omega / 24 \mathrm{~V}, 0-1200 \Omega / 30 \mathrm{~V}$ |
| Total Load (sink + source) | $600 \Omega / 18 \mathrm{~V}, 900 \Omega / 24 \mathrm{~V}, 1200 \Omega / 30 \mathrm{~V}$ |
| PLC Update Rate | 1 channel per scan maximum (D2-230 CPU) <br> 8 channels per scan maximum (D2-240, <br> $\mathrm{D} 2-250(-1) ~ a n d ~ D 2-260 ~ C P U s) ~$ |
| Conversion Settling Time | $400 \mu \mathrm{~s}$ maximum (full scale change) |


| Linearity Error (end to end) | $\pm 2$ count ( $\pm 0.050 \%$ of full scale) maximum |
| :---: | :---: |
| Full Scale Calibration Error | $\pm 12$ counts max. sinking @ any load <br> $\pm 12$ counts max. sourcing @ $125 \Omega$ load <br> $\pm 18$ counts max. sourcing @ $250 \Omega$ load <br> $\pm 26$ counts max. sourcing @ $400 \Omega$ load |
| Offset Calibration Error | $\pm 9$ counts max. sinking @ any load <br> $\pm 9$ counts max. sourcing @ $125 \Omega$ load <br> $\pm 11$ counts max. sourcing @ $250 \Omega$ load <br> $\pm 13$ counts max. sourcing @ $400 \Omega$ load |
| Maximum Full Scale Inaccuracy @ 60C | $\begin{aligned} & 0.5 \% \text { sinking (any load) sinking \& sourcing @ } \\ & 125 \Omega \text { load } \\ & 0.64 \% \text { sourcing @ } 250 \Omega \text { lood } \\ & 0.83 \% \text { sourcing @ } 400 \Omega \text { load } \end{aligned}$ |
| Maximum Full Scale Inaccuracy @ $25^{\circ} \mathrm{C}$ <br> (Incudes all errors and temp drift) | $\begin{aligned} & 0.3 \% \text { sinking (any load) sinking \& sourcing @ } \\ & 125 \Omega \text { load } \\ & 0.44 \% \text { sourcing @ } 250 \Omega \text { load } \\ & 0.63 \% \text { sourcing @ } 400 \Omega \text { load } \end{aligned}$ |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $60^{\circ} \mathrm{C}$ ) |
| Storage Temperature | -4 to $158^{\circ} \mathrm{F}\left(-20\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5\% to 95\% (non-condensing) |
| Environmental air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-1610CON |

## F2-08DA-1 8-Channel 4-20mA Analog Output



NOTE 1: Shields should be connected to the OV of the module.

## Chapter 3: I/O Wiring and Specifications

## F2-02DA-2 2-Channel Voltage Analog Output Module

| This module requires a 24 VDC user power supply for operation. See the F2-02DA-2L on the next page if you want to use a 12 VDC supply. All other specifications are the same. |  |
| :---: | :---: |
| Number of Channels | 2 |
| Output Ranges | 0 to 5V, 0 to $10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$ |
| Resolution | 12 bit (1 in 4096) |
| Output Type | Single ended, 1 common |
| Digital Output Points Required | 16 (Y) output points (12 binary data bits, 2 channel ID bits) |
| Peak Output Voltage | 15 VDC (clamped by transient voltage suppressor) |
| Load Impedance | $2000 \Omega$ minimum |
| Load Capacitance | . $01 \mu \mathrm{~F}$ maximum |
| PLC Update Rate | 1 channel per scan maximum D2-230 CPU 2 channels per scan maximum (D2-240, D2-$250(-1)$ and D2-260 CPUs) |
| Linearity Error (end to end) | $\pm 1$ count ( $0.025 \%$ of full scale) maximum |
| Conversion Settling Time | $5 \mathrm{us} \mathrm{maximum} \mathrm{(full} \mathrm{scale} \mathrm{change)}$ |
| Full Scale Calibration Error (offset error included) | $\pm 12$ counts max. unipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ <br> $\pm 16$ counts max. bipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Offset Calibration Error | $\pm 3$ counts max., unipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ $\pm 8$ counts max., bipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ full scale calibration change (including maximum offset change of 2 counts) |
| Maximum Inaccuracy | $+0.3 \%$ unipolar ranges @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ $\pm 0.45 \%$ unipolar ranges $>77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ $\pm 0.4 \%$ bipolar ranges @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ $\pm 0.55 \%$ bipolar ranges $>77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Base Power Required 5VDC | 40 mA |
| External Power Supply | 18 to 30 VDC, 60 mA (outputs fully loaded) |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ |
| Storage Temperature | $-4^{0}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## F2-02DA-2 2-Channel Voltage Analog Output



NOTE 1: Shields should be connected to the OV of the module or the OV of the R/S.
NOTE 2: Unused voltage outputs should remain open (no connections) for minimum power consumption.

## Chapter 3: I/O Wiring and Specifications

## F2-02DA-2L 2-Channel Voltage Analog Output Module

| This module requires a 12 VDC user power supply for operation. See the F2-02DA-2 on the previous page if you want to use a 24 VDC supply. All other specifications are the same. |  |
| :---: | :---: |
| Number of Channels | 2 |
| Output Ranges | 0 to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V}, \pm 5 \mathrm{~V}, \pm 10 \mathrm{~V}$ |
| Resolution | 12 bit (1 in 4096) |
| Output Type | Single ended, 1 common |
| Digital Output Points Required | 16 (Y) output points (12 binary data bits, 2 channel ID bits) |
| Peak Output Voltage | 15 VDC <br> (clamped by transient voltage suppressor) |
| Load Impedance | $2000 \Omega$ minimum |
| Load Capacitance | . 01 山F maximum |
| PLC Update Rate | 1 channel per scan maximum (D2-230 CPU) <br> 2 channels per scan maximum (D2-240, <br> D2-250(-1) and D2-260 CPUs) |
| Linearity Error (end to end) | $\pm 1$ count ( $0.025 \%$ of full scale) maximum |
| Conversion Settling Time | 5 s maximum (tull scale change) |
| Full Scale Calibration Error (offset error included) | $\pm 12$ counts max. unipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ <br> $\pm 16$ counts max. bipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Offset Calibration Error | $\pm 3$ counts max., unipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ $\pm 8$ counts max., bipolar @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ full scale calibration change (including maximum offset change of 2 counts) |
| Maximum Inaccuracy | $+0.3 \%$ unipolar ranges @ $77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ $\pm 0.45 \%$ unipolar ranges $>77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ $\pm 0.4 \%$ bipolar ranges @770F ( $25^{\circ} \mathrm{C}$ ) $\pm 0.55 \%$ bipolar ranges $>77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right)$ |
| Base Power Required 5VDC | 40 mA |
| External Power Supply | 10 to $15 \mathrm{VDC}, 70 \mathrm{~mA}$ (outputs fully loaded) |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $60^{\circ} \mathrm{C}$ ) |
| Storage Temperature | $-4^{\circ}$ to $158^{8} \mathrm{~F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental Air | No corrosive gases permitted |
| Shock \& Vibration | MLL STD 810C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## F2-02DA-2L 2-Channel Voltage Analog Output



NOTE 1: Shields should be connected to the OV of the module or the OV of the P/S.
NOTE 2: Unused voltage outputs should remain open (no connections) for minimum power consumption.

## F2-02DAS-2 2-Channel 0-5V, 0-10V Isolated Analog Output Module

| Number of Channels | 2 , isolated |
| :--- | :--- |
| Output Ranges | $0-5 \mathrm{~V}, 0-10 \mathrm{~V}$ |
| Resolution | 16 bit (1 in 65536) |
| Output Type | Sourced through external loop supply |
| Digital Output Points <br> Required | 32 (Y) output points <br> (16 binary data bits, 2 channel ID bits) |
| Isolation Voltage | $\pm 750 \mathrm{~V}$ continuous, channel to channel, <br> channel to logic |
| Base Power Required 5VDC | 60 mA |
| External Power Supply | $21.6-26.4 \mathrm{VDC}$ @ 60 mA per channel |
| Load Impedance | $2 \mathrm{k} \Omega$ min |
| PLC Update Rate | 1 channel per scan maximum (D2-230 CPU) <br> 2 2 channels per scan maximum (D2-240, D2- <br> $250(-1)$ and D2-260 CPUs) |
| Conversion Settling Time | $3 \mathrm{~ms} \mathrm{to} \mathrm{0.1} \mathrm{\%} \mathrm{of} \mathrm{full} \mathrm{scale}$ |
| Lin |  |


| Linearity Error (end to end) | $\pm 10$ count ( $\pm 0.015 \%$ of full scale) maximum |
| :---: | :---: |
| Gain Calibration Error | $\pm 32$ counts ( $\pm 0.05 \%$ ) |
| Offset Calibration Error | $\pm 13$ counts ( $\pm 0.02 \%$ ) |
| Output Drift | $50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |
| Maximum Inaccuracy | $0.07 \%$ @ $25^{\circ} \mathrm{C}$ (770F) $0.18 \% 0$ to $60^{\circ} \mathrm{C}$ ( $32^{\circ}$ to $140^{\circ} \mathrm{F}$ ) |
| Operating Temperature | $0^{\circ}$ to $60^{\circ} \mathrm{C}\left(32^{\circ}\right.$ to $\left.140^{\circ} \mathrm{F}\right)$ |
| Storage Temperature | $-20^{\circ}$ to $70^{\circ} \mathrm{C}\left(-4^{0}\right.$ to 1588\%) |
| Relative Humidity | 5 to 95\% (non-condensing) |
| Environmental air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810 C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

## F2-02DAS-2 2-Channel 0-5V, 0-10V Isolated Analog Output



NOTE 1: Shields should be connected to the OV of the module or the OV of the P/S.

## F2-08DA-2 8-Channel Voltage Analog Output Module

| Number of Channels | 8, single-ended, 1 common |
| :---: | :---: |
| Output Ranges | 0 to 5V, 0 to 10V |
| Resolution | 12 bit (1 in 4096) |
| Output Type | Voltage sourcing |
| Digital Output Points Required | 16 (Y) output points <br> (12 binary data bits, 3 channel ID bits, 1 output enable bit) |
| Base Power Required 5VDC | 60 mA |
| External Power Supply | 21.6-26.4 VDC, 140 mA (outputs fully loaded) |
| Peak Output Voltage | 15 VDC (clamped by transient voltage suppressor) |
| Load Impedance | $1-10 \mathrm{k} \Omega$ |
| Load Capacitance | $0.01 \mu \mathrm{~F}$ maximum |
| PLC Update Rate | 1 channel per scan maximum (D2-230 CPU) 8 channels per scan maximum (D2-240, D2-250(-1) and D2-260 CPUs) |
| Conversion Settling Time | 400 us maximum (full scale change) 4.5 ms to 9 ms for digital out to analog out |


| Linearity Error (end to end) | $\pm 1$ count ( $\pm 0.025 \%$ of full scale) maximum |
| :--- | :--- |
| Full Scale Calibration Error | $\pm 12$ counts max. unipolar @ $25^{\circ} \mathrm{C}\left(77^{\circ} \mathrm{F}\right)$ |
| Offset Calibration Error | $\pm 3$ counts max., unipolar @ $25^{\circ} \mathrm{C}\left(77^{\circ} \mathrm{F}\right)$ |
| Accuracy vs. Temperature | $\pm 57$ ppm/ ${ }^{\circ} \mathrm{C}$ full scale calibration change <br> (including maximum offset change of 2 counts) |
| Maximum Inaccuracy | $\pm 0.3 \% ~ @ ~$ <br> $5^{\circ} \mathrm{C}\left(77^{\circ} \mathrm{F}\right)$ <br> $\pm 0.45 \% ~ @ ~$ <br> $-60^{\circ} \mathrm{C}\left(32-140^{\circ} \mathrm{F}\right)$ |
| Operating Temperature | $0^{\circ}$ to $60^{\circ} \mathrm{C} \mathrm{(32}^{\circ}$ to $\left.140^{\circ} \mathrm{F}\right)$ |
| Storage Temperature | $-20^{\circ}$ to $70^{\circ} \mathrm{C}\left(-4^{\circ}\right.$ to $\left.158^{\circ} \mathrm{F}\right)$ |
| Relative Humidity | 5 to $95 \%$ (non-condensing) |
| Environmental air | No corrosive gases permitted |
| Shock \& Vibration | MIL STD 810 C 514.2 |
| Noise Immunity | NEMA ICS3-304 |
| Terminal Type (included) | Removable; D2-810CON |

One count in the specification table is equal to one least significant bit of the analog data value (1 in 4096).

## Chapter 3: I/O Wiring and Specifications

## F2-08DA-2 8-Channel Voltage Analog Output




NOTE 1: Shields should be connected to the OV of the module.

## Chapter 3: I/O Wiring and Specifications

## DL205 Combination Analog I/O Modules

F2-04AD2DA 4-Channel Analog Input / 2-Channel Analog Output Module

| Number of Input Channels | 4, single-ended (1 common) |
| :--- | :--- |
| Number of Output Channels | 2 , single-ended (1 common) |
| Ranges | 4 to 20 mA current (current sinking) |
| Resolution | 12 bit (1 in 4096) |
| Peak Withstanding Voltage | 75 VDC, current outputs |
| Max. Continuous Overload | -40 to +40 mA, each current output |
| Input Impedance | $250 \Omega, \pm 0.1 \%, 1 / 2 \mathrm{~W}$, |
| $25 \mathrm{ppm} / \mathrm{C}$ current input resistance |  |
| External Load Resistance | $0 \Omega$ minimum, current outputs |
| Maximum Loop Supply | 30 VDC |
| Recommended Fuse | 0.032 A, series 217 fast-acting, current inputs |
| Maximum Load/Power | $910 \Omega / 24 \mathrm{~V}$, current outputs |
| Supply | $620 \Omega / 18 \mathrm{~V}, 1200 \Omega / 30 \mathrm{~V}$ |
| Active Low-pass Filter | $-3 \mathrm{~dB} @ 20 \mathrm{~Hz}, 2$ poles (-12 dB per octave) |
| Linearity Error (best fit) | $\pm 1$ count ( $\pm 0.025 \%$ of full scale) maximum |
| Output Settling Time | $100 ~ \mu \mathrm{~s} \mathrm{maximum} \mathrm{(full} \mathrm{scale} \mathrm{change)}$ |
|  |  |


| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ full scale calibration change (including maximum offset change) |  |
| :---: | :---: | :---: |
| Maximum Inaccuracy | $\begin{aligned} & \pm 0.1 \% @ 77^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C}\right) \\ & \pm 0.3 \% @ 32 \text { to } 140^{\circ} \mathrm{F}\left(0 \text { to } 60^{\circ} \mathrm{C}\right) \end{aligned}$ |  |
| Digital Input and Output Points Required | 16 (X) input points (12 binary data bits, 2 channel ID bits, 2 diagnostic bits) 16 (Y) output points (12 binary data bits, 2 channel enable bits) |  |
| PLC Update Rate | 4 channels per scan maximum: (D2-240, D2-250(-1) and D2-260 CPUs) 2 output channels per scan maximum: (D2-240, D2-250(-1) and D2-260 CPUs) 1 input and 1 output channel per scan maximum: (D2-230 CPU) |  |
| Base Power Required 5VDC | 90 mA |  |
| External Power Supply Requirement | 18-26.4 VDC @ 80 mA 20 mA per loop |  |
| Operating Temperature | $32^{\circ}$ to $140^{\circ} \mathrm{F}\left(0^{\circ}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ |  |
| Storage Temperature | $-4^{\circ}$ to $158^{\circ} \mathrm{F}\left(-20^{\circ}\right.$ to $\left.70^{\circ} \mathrm{C}\right)$ |  |
| Relative Humidity | 5 to 95\% (non-condensing) |  |
| Environmental Air | No corrosive gases permitted | One count in the specificatio |
| Shock \& Vibration | MIL STD 810C 514.2 | table is equal to one least significant bit of the analog |
| Noise Immunity | NEMA ICS3-304 |  |
| Terminal Type (included) | Removable; D2-8IOCON |  |

## F2-04AD2DA 4-Channel Analog Input / 2-Channel Analog Output Module



Note 1: Shields should be connected at their respective signal source.
Note 2: Unused channel should remain open for minimum power consumption.
Note 3: More than one external power supply can be used provided the power supply commons are connected.

Note 4: A Series 217, 0.032A fast-acting fuse is recommended for 4-20 mA current input loops.

Note 5: If the power supply common of an external power supply is not connected to 0 VDC on the module, then the output of the external transmitter must be isolated. To avoid "ground loop" errors, recommended 4-20 mA transmitter types are: 2 or 3 wire: isolation between Input signal and power supply 4 wire: Isolation between input signal, power supply, and 4-20 mA output.

Note 6: If an analog channel is connected backwards, then erroneous data values will be returned for that channel.
Note 7: To avoid small errors due to terminal block losses, connect 0 VDC, IN-, and OUT- on the terminal block as shown. The module's internal connection alone of these nodes is not sufficient to permit module performance up to the accuracy specifications.
Note 8: Choose an output transducer resistance according to the maximum load/power listed in the Output Specifications.

## F2-08AD4DA-1 8-Channel Analog Current Input / 4-Channel Analog Current Output Module

NOT SUPPORTED BY D2-230 AND D2-240 CPUs.

| Input Channels per Module | 8, single ended (one common) |
| :---: | :---: |
| Input Range | 0 to 20 mA |
| Resolution | 12, 14, 16-bit selectable |
| External DC Power Required | 100 mA @ 18-26.4 VDC |
| Max. Continuous Overload | $\pm 45 \mathrm{~mA}$ |
| Input Impedance | $100 \Omega 0.1 \% 1 / 4 \mathrm{~W}$ |
| Filter Characteristics | Active low pass, -3dB @ 80 Hz |
| Conversion Time | 12 -bit $=1.5 \mathrm{~ms}$ per channel 14 -bit $=6 \mathrm{~ms}$ per channel 16 -bit $=25 \mathrm{~ms}$ per channel |
| Conversion Method | Over sampling successive approximation |
| Accuracy vs. Temperature | $\pm 25 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ Max. |
| Maximum Inaccuracy | 0.1\% of range |
| Linearity Error (End to End) | 12 -bit $= \pm 2$ count max. ( $\pm 0.06 \%$ of range) 14 -bit $= \pm 10$ count max. $( \pm 0.06 \%$ of range $)$ 16 -bit $= \pm 20$ count max. ( $\pm 0.06 \%$ of range) Monotonic with no missing codes |
| Full Scale Calibration Error (not including offset error) | $\pm 0.07 \%$ of range max. |
| Offset Calibration Error | $\pm 0.03 \%$ of range max. |
| Rec. Fuse (external) | 0.032A, Littelfuse Series 217 fast-acting |
| Base Power Required 5VDC | 35 mA |
| Output Channels per Module | 4 |
| Output Range | 4 to 20 mA |
| Resolution | 16-bit, $0.244 \mathrm{~mA} / \mathrm{bit}$ |
| Output Type | Current sourcing at 20 mA max. |
| Load Impedance | 0-750 $\Omega$ |
| Max. Inaccuracy | 0.25\% of range |
| Max. Full Scale Calibration Error (not incl. offset error) | $\pm 0.075 \%$ of range max. |
| Max. Offset Calibration Error | $\pm 0.1 \%$ of range max. |
| Accuracy vs. Temperature | $\pm 25 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ max. full scale calibration change ( $\pm 0.0025 \%$ of range $/{ }^{\circ} \mathrm{C}$ ) |
| Max. Crosstalk at DC, 50/60Hz | -70 dB, 1 LSB |

## F2-08AD4DA-1 8-Channel Analog Current Input / 4-Channel Analog Current Output

| Linearity Error (End to End) | $\pm 1$ count max. ( $\pm 0.005 \%$ of full scale) <br> Monotonic witt <br> no |
| :--- | :--- |
| Ouspsing codes <br> and Repeatability | $\pm 1$ LSB after 10 min. warm-up typical |
| Output Ripple | $0.005 \%$ of full scale |
| Output Settling Time | 0.5 ms max., 5 us min. (full scale change) |
| Max. Continuous Overload | Outputs open circuit protected |
| Type of Output Protection | Electronically current limited to 20 mA or <br> less |
| Output Signal at <br> Power-up and Power-down | 4 mA |
| Terminal Type (included) | Removable; D2-1610con |



Note 1: A Littlefuse Series 217, 0.032A fast-acting fuse is recommended for all $4-20 \mathrm{~mA}$ current loop inputs.
Note 2: Connect shields to the 0 V of the module; do not connect both ends of shield.

## F2-08AD4DA-2 8-Channel Analog Voltage Input / 4-Channel Analog Voltage Output Module

| Input Channels per Module | 8, single ended (one common) |
| :---: | :---: |
| Input Range | 0 to 10 V |
| Resolution | 12, 14, 16-bit selectable |
| External DC Power Required | 80 mA @ 18-26.4 VDC |
| Max. Continuous Overload | $\pm 100 \mathrm{~V}$ |
| Input Impedance | $>10 \mathrm{M} \Omega$ |
| Filter Characteristics | Active low pass, -3 dB @ 80Hz |
| Conversion Time | 12-bit $=1.5 \mathrm{~ms}$ per channel <br> 14-bit $=6 \mathrm{~ms}$ per channel <br> 16 -bit $=25 \mathrm{~ms}$ per channe |
| Conversion Method | Over sampling successive approximation |
| Accuracy vs. Temperature | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ Max. |
| Maximim Inaccuracy | 0.1\% of range |
| Linearity Error (End to End) |  |
| Full Scale Calibration Error (not including offset error) | $\pm 0.075 \%$ of range max. |
| Offset Calibration Error | $\pm 0.025 \%$ of range max. |
| Base Power Required 5VDC | 35 mA |


| Output Channels per Module | 4 |
| :--- | :--- |
| Output Range | $0-5 \mathrm{~V}, 0-10 \mathrm{~V}$ |
| Resolution | 0 to 5 V at 15 -bit, 0 to10V at 16 -bit, $152 \mu \mathrm{~V} /$ bit |
| Output Type | Voltage sourcing/sinking at 10 mA max. |
| Load Impedance | $>1000 \Omega$ |
| Max. Inaccuracy | $0.15 \%$ of range |
| Max. Full Scale Calibration <br> Error (not incl. offset error) | $\pm 0.075 \%$ of range max. |
| Max. Offset Calibration Error | $\pm 0.025 \%$ of range max. |
| Accuracy vs. Temperature | $\pm 50$ ppm $/{ }^{\circ} \mathrm{C}$ max. full scale calibration change <br> $( \pm 0.005 \%$ <br> of range $\left./{ }^{\circ} \mathrm{C}\right)$ |
| Max. Crosstalk <br> @ DC, $50 / 60 \mathrm{~Hz}$ | $-70 \mathrm{~dB}, 1 \mathrm{LSB}$ |

## F2-08AD4DA-2 8-Channel Analog Voltage Input / 4-Channel Analog Voltage

## Output

| Linearity Error (End to End) | $\pm 1$ count max. ( $\pm 0.0025 \%$ of full scale) <br> Monotonic witt no missing codes |
| :--- | :--- |
| Output Stability and <br> Repeatability | $\pm 1$ LSB after 10 min. warm-up typical |
| Output Ripple | $0.005 \%$ of full scale |
| Output Settling Time | 0.5 ms max., 5 5us min. (full scale change) |
| Max. Continuous Overload | Outputs current limited to 15 mA typical |
| Type of Output Protection | 1 VCl peak output voltage <br> (clamped by transient voltage suppressor) |
| Output Signal at <br> Power-up and Power-down | OV |
| Terminal Type (included) | Removable; D2-16IOCON |



## Chapter 3: I/O Wiring and Specifications

## Glossary of Specification Terms

## Inputs or Outputs Per Module

Indicates number of input or output points per module and designates current sinking, current sourcing, or either.
Commons Per Module
Number of commons per module and their electrical characteristics.

## Input Voltage Range

The operating voltage range of the input circuit.

## Output Voltage Range

The operating voltage range of the output circuit.

## Peak Voltage

Maximum voltage allowed for the input circuit.

## AC Frequency

AC modules are designed to operate within a specific frequency range.

## ON Voltage Level

The voltage level at which the input point will turn ON.

## OFF Voltage Level

The voltage level at which the input point will turn OFF.

## Input impedance

Input impedance can be used to calculate input current for a particular operating voltage.

## Input Current

Typical operating current for an active (ON) input.

## Minimum ON Current

The minimum current for the input circuit to operate reliably in the ON state.

## Maximum OFF Current

The maximum current for the input circuit to operate reliably in the OFF state.

## Minimum Load

The minimum load current for the output circuit to operate properly.

## External DC Required

Some output modules require external power for the output circuitry.

## ON Voltage Drop

Sometimes called "saturation voltage", it is the voltage measured from an output point to its common terminal when the output is ON at max. load.

## Maximum Leakage Current

The maximum current a connected maximum load will receive when the output point is OFF.

## Maximum Inrush Current

The maximum current used by a load for a short duration upon an OFF to ON transition of a output point. It is greater than the normal ON state current and is characteristic of inductive loads in AC circuits.

## Base Power Required

Power from the base power supply is used by the DL205 input modules and varies between different modules. The guidelines for using module power is explained in the power budget configuration section in Chapter 4-7.

## OFF to ON Response

The time the module requires to process an OFF to ON state transition.

## ON to OFF Response

The time the module requires to process an ON to OFF state transition.

## Terminal Type

Indicates whether the terminal type is a removable or non-removable connector or a terminal.

## Status Indicators

The LEDs that indicate the ON/OFF status of an input point. These LEDs are electrically located on either the logic side or the field device side of the input circuit.

## Fuses

Protective devices for an output circuit, which stop current flow when current exceeds the fuse rating. They may be replaceable or non-replaceable, or located externally or internally.

## European Union Directives (CE)



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## Appendix A: European Union Directives (CE)

## European Union (EU) Directives


#### Abstract

NOTE: The information contained in this section is intended as a guideline and is based on our interpretation of the various standards and requirements. Since the actual standards are issued by other parties, and in some cases governmental agencies, the requirements can change over time without advance warning or notice. Changes or additions to the standards can possibly invalidate any part of the information provided in this section.


This area of certification and approval is absolutely vital to anyone who wants to do business in Europe. One of the key tasks that faced the EU member countries and the European Economic Area (EEA) was the requirement to bring several similar yet distinct standards together into one common standard for all members. The primary purpose of a single standard was to make it easier to sell and transport goods between the various countries and to maintain a safe working and living environment. The Directives that resulted from this merging of standards are now legal requirements for doing business in Europe. Products that meet these Directives are required to have a CE mark to signify compliance.

## Member Countries

As of January 1, 2007, the members of the EU are Austria, Belgium, Bulgaria, Cyprus, Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Ireland, Italy, Latvia, Lithonia, Luxembourg, Malta, Netherlands, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, and United Kingdom. Iceland, Liechtenstein, and Norway together with the EU members make up the European Economic Area (EEA) and all are covered by the Directives.

## Applicable Directives

There are several Directives that apply to our products. Directives may be amended, or added, as required.

- Electromagnetic Compatibility Directive (EMC) - this Directive attempts to ensure that devices, equipment, and systems have the ability to function satisfactorily in an electromagnetic environment without introducing intolerable electromagnetic disturbance to anything in that environment.
- Machinery Safety Directive - this Directive covers the safety aspects of the equipment, installation, etc. There are several areas involved, including testing standards covering both electrical noise immunity and noise generation.
- Low Voltage Directive - this Directive is also safety related and covers electrical equipment that has voltage ranges of $50-1000 \mathrm{VAC}$ and/or $75-1500 \mathrm{VDC}$.
- Battery Directive - this Directive covers the production, recycling, and disposal of batteries.


## Compliance

Certain standards within each Directive already require mandatory compliance. The EMC Directive, which has gained the most attention, became mandatory as of January 1, 1996. The Low Voltage Directive became mandatory as of January 1, 1997.
Ultimately, we are all responsible for our various pieces of the puzzle. As manufacturers, we must test our products and document any test results and/or installation procedures that are necessary to comply with the Directives. As a machine builder, you are responsible for
installing the products in a manner which will ensure compliance is maintained. You are also responsible for testing any combinations of products that may (or may not) comply with the Directives when used together. The end user of the products must comply with any Directives that may cover maintenance, disposal, etc. of equipment or various components. Although we strive to provide the best assistance available, it is impossible for us to test all possible configurations of our products with respect to any specific Directive. Because of this, it is ultimately your responsibility to ensure that your machinery (as a whole) complies with these Directives and to keep up with applicable Directives andlor practices that are required for compliance.
As of January 1, 1999, the DL05, DL06, DL205, DL305, and DL405 PLC systems manufactured by Koyo Electronics Industries, FACTS Engineering or HOST Engineering, when properly installed and used, conform to the Electromagnetic Compatibility (EMC), Low Voltage Directive, and Machinery Directive requirements of the following standards.

- EMC Directive Standards Relevant to PLCs EN50081-1 Generic emission standard for residential, commercial, and light industry EN50081-2 Generic emission standard for industrial environment.
EN50082-1 Generic immunity standard for residential, commercial, and light industry EN50082-2 Generic immunity standard for industrial environment.
- Low Voltage Directive Standards Applicable to PLCs EN61010-1 Safety requirements for electrical equipment for measurement, control, and laboratory use.
- Product Specific Standard for PLCs EN61131-2 Programmable controllers, equipment requirements and tests. This standard replaces the above generic standards for immunity and safety. However, the generic emissions standards must still be used in conjunction with the following standards:
-EN 61000-3-2 Harmonics
-EN 61000-3-2 Fluctuations
- Warning on Electrostatic Discharge (ESD)

We recommend that all personnel take necessary precautions to avoid the risk of transferring static charges to inside the control cabinet, and clear warnings and instructions should be provided on the cabinet exterior. Such precautions may include, the use of earth straps, similar devices or the powering off of the equipment inside the enclosure before the door is opened.

- Warning on Radio Interference (RFI) This is a class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.


## General Safety

- External switches, circuit breaker or external fusing, are required for these devices.
- The switch or circuit breaker should be mounted near the PLC equipment.

AutomationDirect is currently in the process of changing their testing procedures from the generic standards to the product specific standards.

## Appendix A: European Union Directives (CE)

## Special Installation Manual

The installation requirements to comply with the requirements of the Machinery Directive, EMC Directive and Low Voltage Directive are slightly more complex than the normal installation requirements found in the United States. To help with this, we have published a special manual which you can order:

- DA-EU-M - EU Installation Manual that covers special installation requirements to meet the EU Directive requirements. Order this manual to obtain the most up-to-date information.


## Other Sources of Information

Although the EMC Directive gets the most attention, other basic Directives, such as the Machinery Directive and the Low Voltage Directive, also place restrictions on the control panel builder. Because of these additional requirements it is recommended that the following publications be purchased and used as guidelines:

- BSI publication TH 42073: February 1996 - covers the safety and electrical aspects of the Machinery Directive
- EN 60204-1:1992 - General electrical requirements for machinery, including Low Voltage and EMC considerations
- IEC 1000-5-2: EMC earth grounding and cabling requirements
- IEC 1000-5-1: EMC general considerations

It may be possible for you to obtain this information locally; however, the official source of applicable Directives and related standards is:
The Office for Official Publications of the European Communities L-2985 Luxembourg; quickest contact is via the World Wide Web at http://publications.europa.eu/index_en.htm
Other sources are:
British Standards Institution - Sales Department
Linford Wood
Milton Keynes
MK14 6LE
United Kingdom; the quickest contact is via the World Wide Web at http://www.bsi.org.uk A commercial provider of Standards at www.ihs.com

## Basic EMC Installation Guidelines

## Enclosures

The simplest way to meet the safety requirements of the Machinery and Low Voltage Directives is to house all control equipment in an industry standard lockable steel enclosure. This normally has an added benefit because it will also help ensure that the EMC characteristics are well within the requirements of the EMC Directive. Although the RF emissions from the PLC equipment, when measured in the open air, are well below the EMC Directive limits, certain configurations can increase emission levels. Holes in the enclosure, for the passage of cables or to mount operator interfaces, will often increase emissions.

## AC Mains Filters

The DL305 AC powered base power supplies require extra mains filtering to comply with the EMC Directive on conducted RF emissions. All PLC equipment has been tested with filters from Schaffner, which reduce emissions levels if the filters are properly grounded (earth ground). A filter with a current rating suitable to supply all PLC power supplies and AC input modules should be selected. We suggest the FN2080 for DL305 systems.


NOTE: Very few mains filters can reduce problem emissions to negligible levels. In some cases, filters may increase conducted emissions if not properly matched to the problem emissions.

## Suppression and Fusing

In order to comply with the fire risk requirements of the Low Voltage and Machinery Directive electrical standards (EN 61010-1 and EN 60204-1), by limiting the power into "unlimited" mains circuits with power leads reversed, it is necessary to fuse both AC and DC supply inputs. You should also install a transient voltage suppressor across the power input connections of the PLC. Choose a suppressor such as a metal oxide varistor, with a rating of 275 VAC working voltage for 230 V nominal supplies ( 150 VAC working voltage for 115 V supplies) and high energy capacity (eg. 140 joules).
Transient suppressors must be protected by fuses and the capacity of the transient suppressor must be greater than the blow characteristics of the fuses or circuit breakers to avoid a fire risk. A recommended AC supply input arrangement for Koyo PLCs is to use twin 3 amp TT fused terminals with fuse blown indication, such as DINnectors DN-F10L terminals, or twin circuit breakers, wired to a Schaffner FN2010 filter or equivalent, with high energy transient suppressor soldered directly across the output terminals of the filter. PLC system inputs should also be protected from voltage impulses by deriving their power from the same fused, filtered, and surge-suppressed supply.

## Internal Enclosure Grounding

A heavy-duty star earth terminal block should be provided in every cubicle for the connection of all earth ground straps, protective earth ground connections, mains filter earth ground wires, and mechanical assembly earth ground connections. This should be installed to comply with safety and EMC requirements, local standards, and the requirements found in IEC 1000-5-2.The Machinery Directive also requires that the common terminals of PLC input modules, and common supply side of loads driven from PLC output modules should be connected to the protective earth ground terminal.

## Appendix A: European Union Directives (CE)

## Equi-potential Grounding



Adequate site earth grounding must be provided for equipment containing modern electronic circuitry. The use of isolated earth electrodes for electronic systems is forbidden in some countries. Make sure you check any requirements for your particular destination. IEC 1000-5-2 covers equi-potential bonding of earth grids adequately, but special attention should be given to apparatus and control cubicles that contain I/O devices, remote I/O racks, or have inter-system communications with the primary PLC system enclosure. An equipotential bond wire must be provided alongside all serial communications cables, and to any separate items of the plant which contain I/O devices connected to the PLC. The diagram shows an example of four physical locations connected by a communications cable.

## Communications and Shielded Cables



Good quality 24 AWG minimum twisted-pair shielded cables, with overall foil and braid shields are recommended for analog cabling and communications cabling outside of the PLC enclosure. To date it has been a common practice to only provide an earth ground for one end of the cable shield in order to minimize the risk of noise caused by earth ground loop currents between apparatus. The procedure of only grounding one end, which primarily originated as a result of trying to reduce hum in audio systems, is no longer applicable to the complex industrial environment. Shielded cables are also efficient emitters of RF noise from the PLC system, and can interact in a parasitic manner in networks and between multiple sources of interference.

The recommendation is to use shielded cables as electrostatic "pipes" between apparatus and systems, and to run heavy gauge equi-potential bond wires alongside all shielded cables. When a shielded cable runs through the metallic wall of an enclosure or machine, it is recommended in IEC 1000-5-2 that the shield should be connected over its full perimeter to the wall, preferably using a conducting adapter, and not via a pigtail wire connection to an earth ground bolt. Shields must be connected to every enclosure wall or machine cover that they pass through.

## Analog and RS232 Cables

Providing an earth ground for both ends of the shield for analog circuits provides the perfect electrical environment for the twisted pair cable as the loop consists of signal and return, in a perfectly balanced circuit arrangement, with connection to the common of the input circuitry made at the module terminals. RS232 cables are handled in the same way.

## Multidrop Cables

RS422 twin twisted pair, and RS485 single twisted pair cables also require a 0 V link, which has often been provided in the past by the cable shield. It is now recommended that you use triple twisted pair cabling for RS422 links, and twin twisted pair cable for RS485 links. This is because the extra pair can be used as the 0 V inter-system link. With loop DC power supplies earth grounded in both systems, earth loops are created in this manner via the intersystem 0 V link. The installation guides encourage earth loops, which are maintained at a low impedance by using heavy equi-potential bond wires. To account for non-European installations using single-end earth grounds, and sites with far from ideal earth ground characteristics, we recommend the addition of 100 ohm resistors at each 0 V link connection in network and communications cables.


## Shielded Cables within Enclosures

When you run cables between PLC items within an enclosure which also contains susceptible electronic equipment from other manufacturers, remember that these cables may be a source of RF emissions. There are ways to minimize this risk. Standard data cables connecting PLCs and/or operator interfaces should be routed well away from other equipment and their associated cabling. You can make special serial cables where the cable shield is connected to the enclosure's earth ground at both ends, the same way as external cables are connected.

## Appendix A: European Union Directives (CE)

## Analog Modules and RF Interference

All Automationdirect products are tested to withstand field strength levels up to $10 \mathrm{~V} / \mathrm{m}$, which is the maximum required by the relevant EU standards. While all products pass this test, analog modules will typically exhibit deviations of their readings. This is quite normal; however, systems designers should be aware of this and plan accordingly.
When assembling a control system using analog modules, these issues must be adhered to and should be integrated into the system design. This is the responsibility of the system builder/commissioner.

## Network Isolation

For safety reasons, it is a specific requirement of the Machinery Directive that a keyswitch that isolates any network input signal during maintenance must be provided, so that remote commands cannot be received that could result in the operation of the machinery. The FA-ISOCON does not have a keyswitch! Use a keylock and switch on your enclosure, which, when open, removes power from the FA-ISOCON. To avoid the introduction of noise into the system, any keyswitch assembly should be housed in its own earth grounded steel box and the integrity of the shielded cable must be maintained.
Again, for further information on EU directives we recommend that you get a copy of our EU Installation Manual (DA-EU-M). Also, if you are connected to the World Wide Web, you can check the EU Commission's official site at: http://ec.europa.eu/index_en.htm.

## DC Powered Versions

Due to slightly higher emissions radiated by the DC powered versions of the DL205, and the differing emissions performance for different DC supply voltages, the following stipulations must be met:

- The PLC must be housed within a metallic enclosure with a minimum amount of orifices.
- I/O and communications cabling exiting the cabinet must be contained within metallic conduit/trunking.


## Items Specific to the DL205

- The rating between all circuits in this product are rated as basic insulation only, as appropriate for single fault conditions.
- There is no isolation offered between the PLC and the analog inputs of this product.
- It is the responsibility of the system designer to earth one side of all control and power circuits, and to earth the braid of screened cables.
- This equipment must be properly installed while adhering to the guidelines of the installation manual DA-EU-M (available for download at AutomationDirect Technical Support Manuals), and the installation standards IEC 1000-5-1, IEC 1000-5-2 and IEC 1131-4.
- It is a requirement that all PLC equipment must be housed in a protective steel enclosure, which limits access to operators by a lock and power breaker. If access is required by operators or untrained personnel, the equipment must be installed inside an internal cover or secondary enclosure. A warning label must be used on the front door of the installation cabinet as follows: Warning: Exposed terminals and hazardous voltages inside.
- It should be noted that the safety requirements of the machinery directive standard EN60204-1 state that all equipment power circuits must be wired through isolation transformers or isolating power supplies, and that one side of all AC or DC control circuits must be earthed.
- Both power input connections to the PLC must be separately fused using 3 amp T-type anti-surge fuses, and a transient suppressor fitted to limit supply overvoltages.
- The user is made aware by notice in the documentation that, if the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

